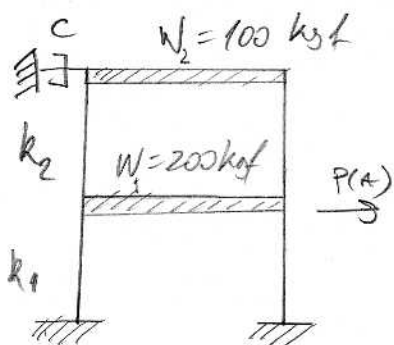
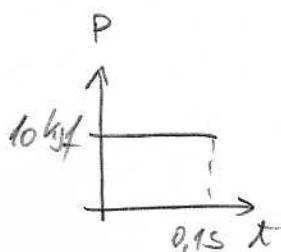


P11



$Q_{max}?$



$$g = 9.8 \text{ m/s}^2$$

$$k_1 = 3000 \text{ ksf/m}$$

$$k_2 = 5000 \text{ ksf/m}$$

$$c = 2 \frac{\text{kof} \cdot \text{s}}{\text{m}}$$

Sol

Edificio de corte:

$$\Rightarrow [M] = \begin{bmatrix} \frac{W_2}{g} & 0 \\ 0 & \frac{W_1}{g} \end{bmatrix} = \begin{bmatrix} 10.204 & 0 \\ 0 & 20.408 \end{bmatrix} \frac{\text{kof} \cdot \text{s}^2}{\text{m}}$$

$$[K] = \begin{bmatrix} k_2 & -k_2 \\ -k_2 & k_1 + k_2 \end{bmatrix} = \begin{bmatrix} 5000 & -5000 \\ -5000 & 8000 \end{bmatrix} \text{ kof/m}$$

$$\Rightarrow [\phi] = \begin{bmatrix} 0.852 & 0.775 \\ -0.523 & 0.631 \end{bmatrix} \quad \omega = \begin{pmatrix} 28.123 \\ 9.543 \end{pmatrix} \frac{\text{rad}}{\text{s}} \Rightarrow T = \frac{2\pi}{\omega} = \begin{pmatrix} 0.223 \\ 0.658 \end{pmatrix} \text{ s}$$

Normalizadas x $[M_{ii}]$, i.e $[\tilde{M}_{ii}] = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$

$$[M_{ii}] = [\phi]^T [M] [\phi] = \begin{bmatrix} 12.999 & 0 \\ 0 & 14.272 \end{bmatrix}$$

$$\{\phi_i\}^T [M] \{\phi_i\} = M_{ii}$$

$$\frac{1}{\alpha} \{\phi_i\}^T [M] \{\phi_i\} \frac{1}{\alpha} = 1$$

$$\frac{M_{ii}}{\alpha^2} = 1 \Rightarrow \alpha = \sqrt{M_{ii}}$$

luego normalizamos: $\{\tilde{\phi}_i\} = \frac{\{\phi_i\}}{\sqrt{M_{ii}}} \Rightarrow [\tilde{\phi}] = \begin{bmatrix} 0.236 & 0.205 \\ -0.145 & 0.167 \end{bmatrix}$

$$[C] = \begin{bmatrix} 2 & 0 \\ 0 & 0 \end{bmatrix} \frac{\text{kgf} \cdot \text{s}}{\text{m}}$$

$$[\tilde{\phi}]^T [C] [\tilde{\phi}] = \begin{bmatrix} 0.112 & 0.097 \\ 0.097 & 0.084 \end{bmatrix} = [C_m]$$

$$[C_m] = \begin{bmatrix} 2M_{m2} \omega_2 \beta_2 \\ 2M_{m1} \omega_1 \beta_1 \end{bmatrix}$$

$$\Rightarrow 2M_{m2} \omega_2 \beta_2 = 0.112$$

$$2M_{m1} \omega_1 \beta_1 = 0.084$$

$$\Rightarrow \beta_1 = 0.0044$$

$$\beta_2 = 0.002$$

Analizamos t_d / T

$$\frac{t_d}{T} = \begin{pmatrix} 0.152 \\ 0.448 \end{pmatrix} \rightarrow \begin{matrix} < 0.25 \rightarrow \text{Impacto corta duraci3n} \\ > 0.25 \rightarrow \text{" larga "} \end{matrix}$$

Por simplicidad, resolver para corta duraci3n (dicho en control)

$$\Rightarrow y_m(t) = \frac{-P_m \omega_m \cdot t}{M_{m1} \omega_{mD}} P_m(t) \cdot \text{sol} \cdot \text{sen}(\omega_D \cdot t) \quad \omega_D \approx \omega$$

$$P_m = \tilde{\phi}^T P = \begin{cases} -0.145 P(t) \\ 0.167 P(t) \end{cases} \rightarrow \begin{matrix} \text{Modo 2} \\ \text{Modo 1} \end{matrix}$$

$$\Rightarrow y_1(t) = 0.0175 \cdot e^{-0.042t} \cdot \text{sen}(9.543t)$$

$$y_2(t) = -0.0052 \cdot e^{-0.056t} \cdot \text{sen}(28.123t)$$

$$\Rightarrow v_{\text{inferior}}(t) = \sum \phi_{i,2} \cdot y_i(t) = \phi_{12} \cdot y_1 + \phi_{22} \cdot y_2$$

$$Q_{\text{base}}(t) = k_1 \cdot v_{\text{inferior}}(t)$$

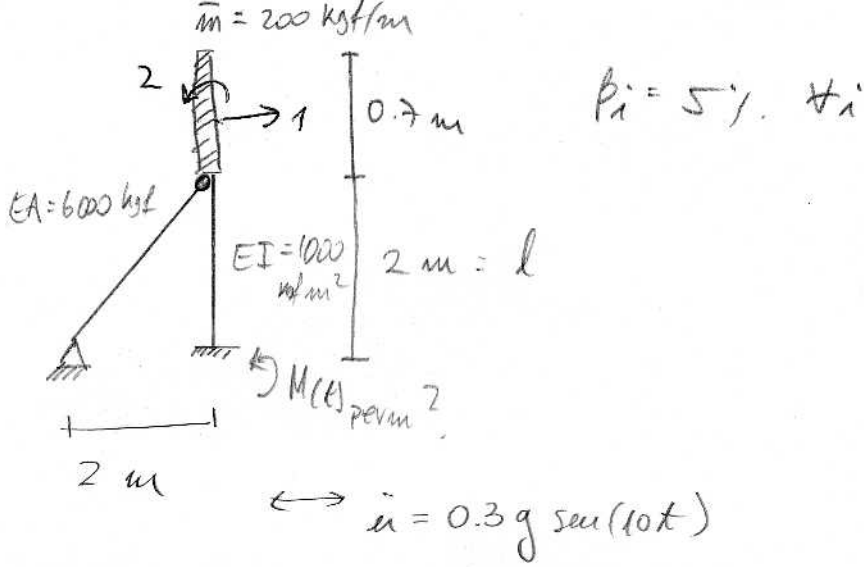
$$\Rightarrow Q_{\text{base}}(t) = 8.767 e^{-0.042t} \text{sen}(9.543 \cdot t) + 2.243 e^{-0.056t} \text{sen}(28.123t)$$

¿ Q_{max} ?

Opci3n a) Graficar en TI $\Rightarrow \text{Max} \approx 8.9 \text{ kgf}$

Opci3n b) Suponer que controla el primer modo

P2



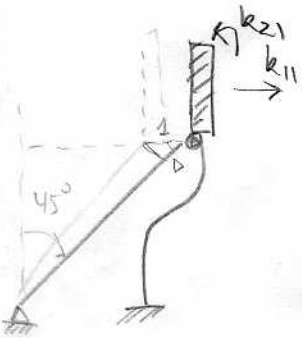
Sol

• Matriz de Masa:

$$[M] = \begin{bmatrix} \frac{\bar{m}}{g} \cdot l_b & 0 \\ 0 & \frac{1}{12} \left(\frac{\bar{m}}{g} l_b \right) l_b^2 \end{bmatrix} = \begin{bmatrix} 14.286 & 0 \\ 0 & 0.583 \end{bmatrix}$$

• Matriz de rigidez

$$u_1 = 1 \quad u_2 = 0$$



$$\Delta = \cos 45^\circ$$

$$F_{B_x} = \frac{AE}{l_b} \cdot \Delta \cdot \cos 45^\circ \cdot x$$

$$\Rightarrow k_{B_x} = \frac{AE}{l_b} \cos^2 45^\circ = \frac{AE}{2\sqrt{2}l}$$

$$k_{11} = \frac{12EI}{l^3} + \frac{EA}{2\sqrt{2}l}$$

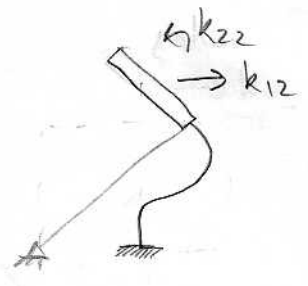
$$k_{12} = \frac{6EI}{l^2} + k_{11} \cdot \frac{l_b}{2}$$

$$= \frac{6EI}{l^2} + \frac{l_b}{2} \left(\frac{12EI}{l^3} + \frac{EA}{2\sqrt{2}l} \right)$$

$$u_1 = 0 \quad u_2 = 1$$

$$l^2 \cdot \frac{1}{2} \left(\frac{1}{l^3} + \frac{1}{2\sqrt{2}l} \right)$$

$$u_1 = 0 \quad u_2 = 1$$



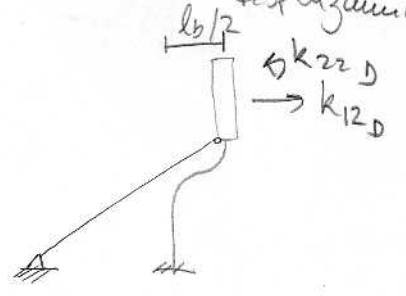
Efecto giro:



$$k_{12g} = \frac{6EI}{l^2}$$

$$k_{22g} = \frac{4EI}{l} + k_{12g} \cdot \frac{l_b}{2}$$

Efecto desplazamiento



$$k_{12D} = \frac{12EI}{l^3} \cdot \frac{l_b}{2} + \frac{AE}{2\sqrt{2}l} \cdot \frac{l_b}{2}$$

$$k_{22D} = \frac{6EI}{l^2} \cdot \frac{l_b}{2} + k_{12D} \cdot \frac{l_b}{2}$$

$$k_{ij} = k_{ijg} + k_{ijD}$$

$$\Rightarrow k_{22D} = \frac{4EI}{l} + \frac{6EI}{l^2} \cdot \frac{l_b}{2} + \frac{6EI}{l^2} \cdot \frac{l_b}{2} + \left(\frac{12EI}{l^3} \cdot \frac{l_b}{2} + \frac{AE}{2\sqrt{2}l} \cdot \frac{l_b}{2} \right) \frac{l_b}{2}$$

Calculando:

$$[K] = \begin{bmatrix} 2561 & 2396 \\ 2396 & 3364 \end{bmatrix} \Rightarrow \phi = \begin{bmatrix} -0.812 & -0.029 \\ 0.584 & -1 \end{bmatrix}$$

Normalizamos:

$$\tilde{\phi}_i = \frac{\phi_i}{\sqrt{M_{m_i}}} \quad [M_m] = \phi^T M \phi = \begin{bmatrix} 9.610 & 0 \\ 0 & 0.595 \end{bmatrix}$$

$$\Rightarrow [\tilde{\phi}] = \begin{bmatrix} -0.262 & -0.038 \\ 0.188 & -1.296 \end{bmatrix}; \quad \omega = \begin{pmatrix} 7.65 \\ 76.727 \end{pmatrix} \frac{\text{rad}}{\text{s}} \quad T = \begin{pmatrix} 0.821 \\ 0.082 \end{pmatrix} \text{s}$$

Para um sistema horizontal, $\{r\} = \begin{Bmatrix} 1 \\ 0 \end{Bmatrix} \Rightarrow L = [\tilde{\phi}]^T [M] \{r\} = \begin{Bmatrix} -3.740 \\ -0.544 \end{Bmatrix}$

recostrar:

$$M_m \ddot{y} + c_m \dot{y} + k_m y = -\{L\} \ddot{u}_g = -L \ddot{u}_{g0} \text{sen}(\bar{\omega}t)$$

Como normalizamos por massa modal:

$$\ddot{y}_i + 2\beta_i \omega_i \dot{y}_i + \omega_i^2 y_i = -L_i \ddot{u}_{g0} \text{sen}(\bar{\omega}t)$$

Sol. em regime permanente:

$$y_i(t) = \frac{P_{0i}}{K_i} \cdot D_i \text{sen}(\bar{\omega}t - \theta_i) \quad \theta_i = \arctan\left(\frac{2\beta_i \gamma_i}{1 - \gamma_i^2}\right) = \begin{pmatrix} -0.182 \\ 0.013 \end{pmatrix} \text{rad}$$

$$\gamma_i = \frac{\bar{\omega}}{\omega_i} = \begin{pmatrix} 1.302 \\ 0.130 \end{pmatrix}$$

$$\gamma_i = \frac{\omega}{\omega_i} = \begin{pmatrix} 1.307 \\ 0.130 \end{pmatrix}$$

$$\Rightarrow D_i = \frac{1}{\sqrt{(1-\gamma_i)^2 + (2\beta_i\gamma_i)^2}} = \begin{pmatrix} 1.388 \\ 1.017 \end{pmatrix}$$

De esta forma

$$y_1(t) = 0.2886 \sin(\bar{\omega}t + 0.182)$$

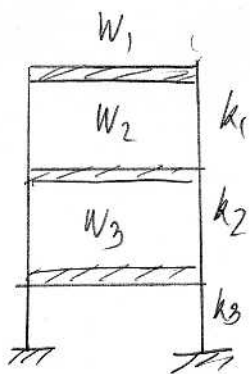
$$y_2(t) = 0.0029 \sin(\bar{\omega}t - 0.013)$$

Además

$$v(t) = [\phi] \{y\} = \begin{Bmatrix} v_1(t) \\ v_2(t) \end{Bmatrix}$$

$$\Rightarrow M_{\text{Base}}(t) = \frac{6EI}{l^2} v_1(t) + \left(\frac{6EI}{l^2} \cdot \frac{l}{2} + \frac{2EI}{l} \right) v_2(t)$$

P3



$$S_a = 0.5g \frac{1 + 4.5 \left(\frac{T}{0.3}\right)^{1.5}}{1 + \left(\frac{T}{0.3}\right)^3}$$

$$\begin{aligned} \ddot{v}_{max} &= ? \\ \Delta v_{max} &= ? \\ Q_{max} & // \\ M_{cols} & // \end{aligned}$$

Sol

Edifício de corte

$$M = \begin{bmatrix} W_1/g & & \\ & W_2/g & \\ & & W_3/g \end{bmatrix}$$

$$K = \begin{bmatrix} k_1 & -k_1 & 0 \\ -k_1 & k_1+k_2 & -k_2 \\ 0 & -k_2 & k_2+k_3 \end{bmatrix}$$

$$\Rightarrow M = \begin{bmatrix} 7.143 & & \\ & 20.408 & \\ & & 20.408 \end{bmatrix}$$

$$K = \begin{bmatrix} 500 & -500 & 0 \\ -500 & 2000 & -1500 \\ 0 & -1500 & 3500 \end{bmatrix}$$

$$\Rightarrow \omega = \begin{pmatrix} 4.904 \\ 9.758 \\ 14.841 \end{pmatrix}$$

$$; T = \begin{pmatrix} 1.281 \\ 0.644 \\ 0.423 \end{pmatrix}$$

$$M_m = \begin{bmatrix} 11.784 & & \\ & 9.797 & \\ & & 19.583 \end{bmatrix}$$

$$\Rightarrow \tilde{\phi} = \frac{\phi_i}{\sqrt{M_{m_i}}} = \begin{bmatrix} 0.235 & -0.286 & 0.056 \\ 0.154 & 0.103 & -0.121 \\ 0.077 & 0.099 & 0.182 \end{bmatrix}$$

$$\{v\} = \begin{Bmatrix} 1 \\ 1 \\ 1 \end{Bmatrix}$$

Factor de corte

Factor de part:

$$\{\alpha\} = [\phi][M]\{r\} = \begin{Bmatrix} 6.394 \\ 2.083 \\ 1.656 \end{Bmatrix} \frac{\text{kgf} \cdot \text{s}^2}{\text{m}}$$

Evalvamos S_a :

$$S_a = \begin{pmatrix} 2.528 \\ 6.818 \\ 10.987 \end{pmatrix} \text{m/s}^2$$

$$\Rightarrow \ddot{v}_{\max} = \left\{ \phi_i \right\} \frac{L_m}{M_m} S_a = \begin{bmatrix} 3.797 & -4.058 & 1.025 \\ 2.493 & 1.461 & -2.201 \\ 1.243 & 1.403 & 3.318 \end{bmatrix} \text{m/s}^2$$

Combinando:

$$\ddot{v}_{\max} = \begin{Bmatrix} 5.651 \\ 3.632 \\ 3.813 \end{Bmatrix}$$

$$v_{max_i} = \frac{\ddot{v}_{max_i}}{\omega_i^2} = \begin{bmatrix} 0.1579 & -0.0426 & 0.0042 \\ 0.1037 & 0.0153 & -0.0100 \\ 0.0517 & 0.0148 & 0.0151 \end{bmatrix} \text{ m}$$

$$\Delta v_{max_i} = \begin{bmatrix} -0.0542 & 0.0580 & -0.0146 \\ -0.0520 & -0.0006 & 0.0251 \\ 0.0517 & 0.0148 & 0.0151 \end{bmatrix} \text{ m}$$

Comb:

$$\Rightarrow \Delta v_{max} = \begin{pmatrix} 0.081 \\ 0.058 \\ 0.056 \end{pmatrix} \text{ m} \quad \underline{\underline{SLS}}$$

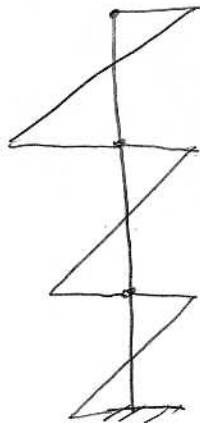
Q_{max}

$$Q_{max_i} = \frac{L_m^2}{K_m} \cdot S_a = \begin{pmatrix} 103.357 \\ 29.546 \\ 30.933 \end{pmatrix} \text{ kJf}$$

Combinação

$$Q_{max} = 111.649 \text{ kJf}$$

Diagrama Momento:



$$\pm \frac{6EI}{l^2} \cdot \Delta v_{ij}$$