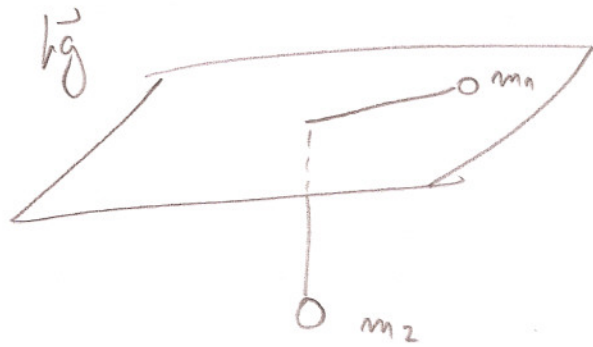
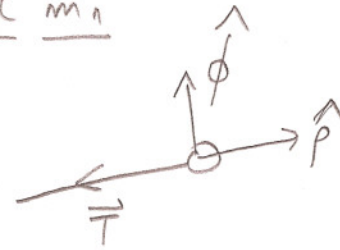


P1)



DCL m_1

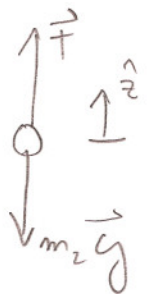


$$\hat{\rho}) -T = m_1(\ddot{\rho} - \rho\dot{\phi}^2) \quad (1)$$

$$\hat{\phi}) 0 = m_1 a_\phi \Rightarrow \rho^2 \dot{\phi} = ct \quad (2)$$

$$\hat{z}) -m_1 g + N = 0 \quad (3)$$

DCL m_2



$$\hat{z}) T - m_2 g = m_2 \ddot{z} \quad (4)$$

$$\ddot{z} = \ddot{\rho}$$

$$(1) + (4) \Rightarrow -m_2 g = (m_1 + m_2) \ddot{\rho} - m_1 \rho \dot{\phi}^2$$

$$\rho^2 \dot{\phi} = \rho_0 v_0 = h = \frac{l}{m}$$

$$\dot{\phi} = \frac{\rho_0 v_0}{\rho^2} = \frac{h}{\rho^2}$$

$$-m_2 g = (m_1 + m_2) \ddot{\rho} - m_1 \frac{h^2}{\rho^3}$$

$$(m_1 + m_2) \ddot{\rho} = -\frac{\partial V_{\text{eff}}}{\partial \rho} = m_1 \frac{h^2}{\rho^3} - m_2 g$$

$$V_{\text{eff}}(\rho) = \frac{m_1 h^2}{2 \rho^2} - m_2 g (l - \rho) \leftarrow \left[\text{calculado a través de Energía} \right]$$

$$\frac{\partial V_{\text{eff}}}{\partial \rho} = 0 \text{ pto eq} \Rightarrow m_1 \frac{h^2}{\rho^3} - m_2 g = 0 \Rightarrow \left(\frac{m_1 h^2}{m_2 g} \right)^{1/3} = \rho_0$$

P2

$$U = \begin{cases} U_1 & x < 0 \\ U_2 & x > 0 \end{cases}$$

$$-\frac{dU}{dy} = F_y = 0$$

$$F_y = m\ddot{y} = 0 \Rightarrow v_y = \text{cte} \quad 1$$

$$v_y = v_1 \sin \theta_1 = v_2 \sin \theta_2 \quad 1$$

Por conservación de la Energía

$$\frac{1}{2} m v_1^2 + U_1 = \frac{1}{2} m v_2^2 + U_2 \quad 2$$

$$v_2^2 = v_1^2 + \frac{2(U_1 - U_2)}{m} \quad 1$$

$$v_2 = \sqrt{v_1^2 + \frac{2(U_1 - U_2)}{m}}$$

$$\frac{\sin \theta_1}{\sin \theta_2} = \frac{v_2}{v_1} = \frac{\sqrt{v_1^2 + \frac{2(U_1 - U_2)}{m}}}{v_1} \quad 1$$

P3)

$$U(x) = \frac{1}{2} K (\sqrt{x^2 + l^2} - l_0)^2$$

$$\frac{dU}{dx} = K \frac{(\sqrt{x^2 + l^2} - l_0) x}{\sqrt{x^2 + l^2}}$$

$$\frac{dU}{dx} = 0 \Rightarrow x(\sqrt{x^2 + l^2} - l_0) = 0$$

$$\Rightarrow x = 0 \quad \vee \quad x^2 = l_0^2 - l^2$$

$$\Rightarrow x = \pm \sqrt{l_0^2 - l^2}$$

es válido si $l_0^2 \geq l^2$

$$\boxed{l_0 \geq l}$$

$$\frac{d^2U}{dx^2} = K \frac{(\sqrt{x^2 + l^2} - l_0)}{\sqrt{x^2 + l^2}} + \frac{K l_0 x^2}{(x^2 + l^2)^{3/2}}$$

$$\underline{x=0} \quad \left. \frac{d^2U}{dx^2} \right|_{x=0} = K \left(\frac{l - l_0}{l} \right)$$

$\Rightarrow x=0$ es ESTABLE si $l > l_0$

$$\Rightarrow \omega_{\text{peq}}^2 \Big|_{x=0} = \frac{K}{m} \left(1 - \frac{l_0}{l} \right)$$

$$\underline{x^2 = l_0^2 - l^2}$$

$$\left. \frac{d^2U}{dx^2} \right|_{x^2 = l_0^2 - l^2} = K \frac{(l_0^2 - l^2)}{l_0^2}$$

$\Rightarrow x = \sqrt{l_0^2 - l^2}$ si $l_0 > l$

$$\Rightarrow \omega_{\text{peq}}^2 = \frac{\left. \frac{d^2U}{dx^2} \right|_{x^2 = l_0^2 - l^2}}{m} = \frac{K}{m} \left(1 - \frac{l^2}{l_0^2} \right)$$

$\Rightarrow x=0$ es pto de eq si $l_0 \leq l$, ya que de esta forma no existe otra eq.