

Campo magnético o inducción magnética

$$\vec{F} = q \vec{E} + q (\vec{v} \times \vec{B}) \text{ Fza. de Lorentz}$$

$\vec{E} =$ Campo eléctrico, $\vec{B} =$ Campo Magnético
 $q(\vec{v} \times \vec{B})$

Unidades

$$N = C \times \frac{m}{s} \times B = \frac{C}{s} \times m \times B = A \times m \times B$$

$$[B] = \left[\frac{N}{A \cdot m} \right] = \text{Tesla } [T]$$

$$1 T = 10^4 \text{ gauss. (cgs)}$$

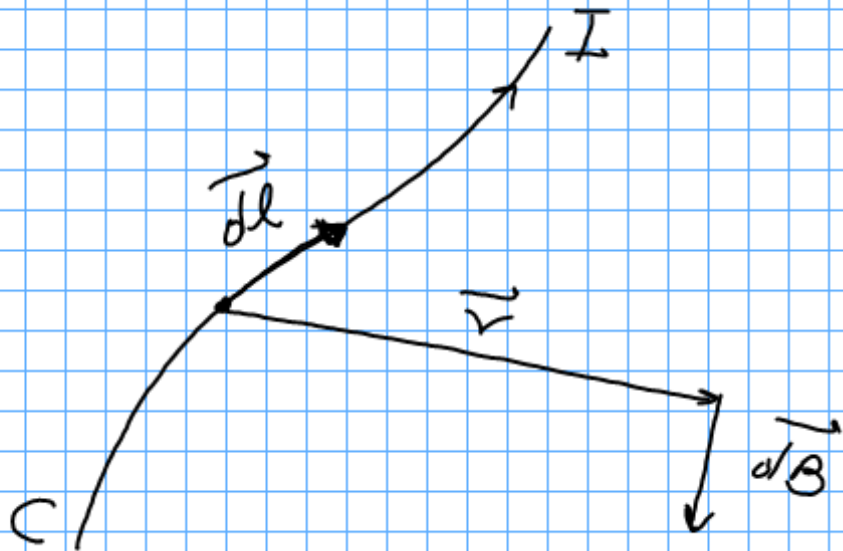
Campo magnético terrestre: 0.3 - 0.6 Gauss = 30000 - 60000 nT

$$1 \text{ nT} = 10^{-9} T = 1 \gamma \text{ (gamma)}$$

$$1 \text{ Gauss} = 100000 \gamma$$

Corrientes eléctricas generan C. Mag.

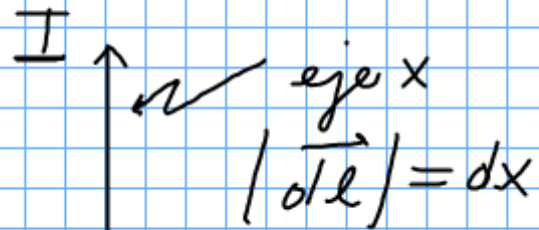
Ley de Biot-Savart



$$\vec{dB} = \frac{\mu_0}{4\pi} \frac{I d\vec{l} \times \hat{r}}{r^2}$$

$$\begin{aligned} \mu_0 &= \text{Permeabilidad del vacío} \\ &= 4\pi \times 10^{-7} \frac{\text{N}}{\text{A}^2} \end{aligned}$$

$$\vec{B} = \frac{\mu_0}{4\pi} \int_C \frac{I d\vec{l} \times \hat{r}}{r^2}$$



$$d\vec{l} \times \hat{r} = dx \sin\theta \hat{e}$$

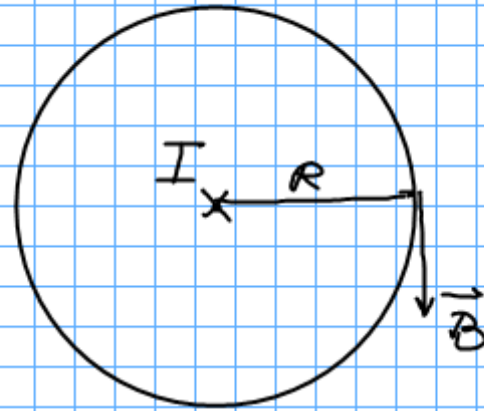
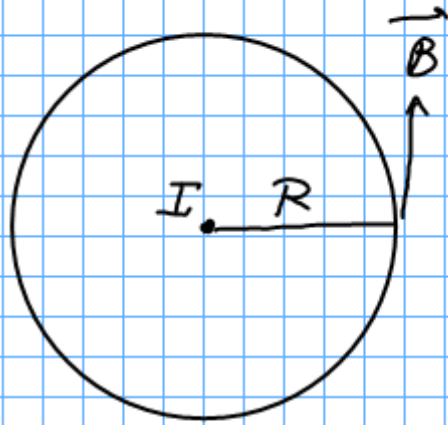
$$dB = \frac{\mu_0 I}{4\pi} \frac{\sin\theta dx}{r^2}$$

$$r = \sqrt{R^2 + x^2}, \quad \sin\theta = \frac{R}{r}$$

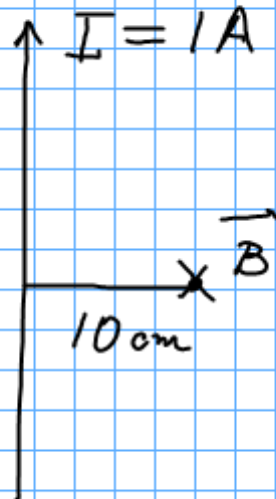
$$B = \frac{\mu_0 I R}{4\pi} \int_{-\infty}^{+\infty} \frac{dx}{(R^2 + x^2)^{3/2}}$$

$$= \frac{\mu_0 I R}{4\pi} \frac{x}{R^2 \sqrt{R^2 + x^2}} \Big|_{-\infty}^{+\infty}$$

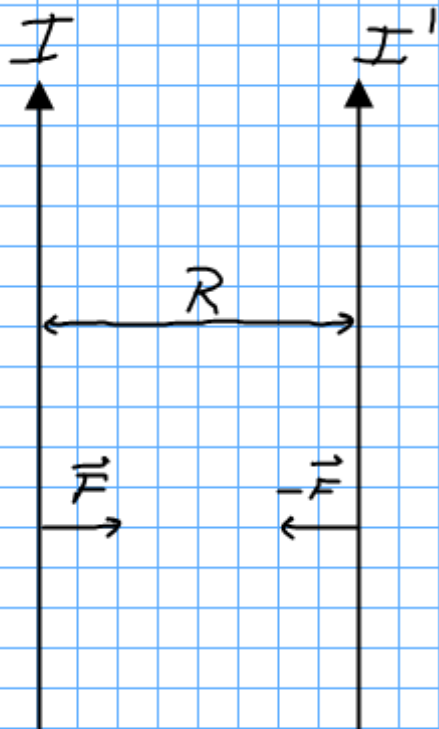
$$\therefore B = \frac{\mu_0 I}{4\pi R} (1+1) = \frac{\mu_0 I}{2\pi R}$$



$$|\vec{B}| = \frac{\mu_0}{2\pi} \frac{I}{R}$$



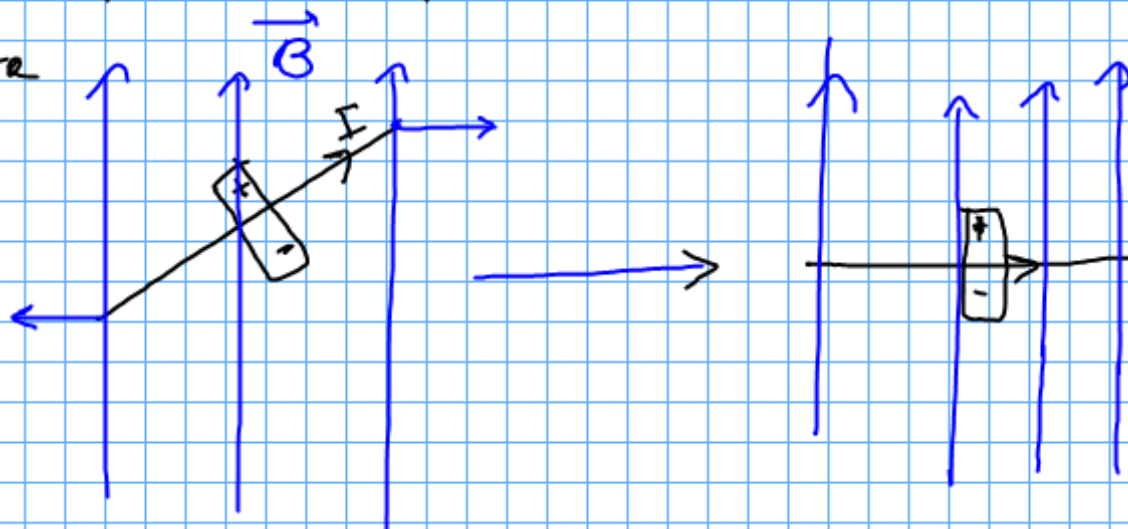
$$\begin{aligned} B &= 2 \frac{\mu_0}{4\pi} \times \frac{1}{0.1} = 2 \times 10^{-7} \times 10 \\ &= 2 \times 10^{-6} \text{ T} \\ &= 2000 \text{ nT} = 2000 \gamma \end{aligned}$$



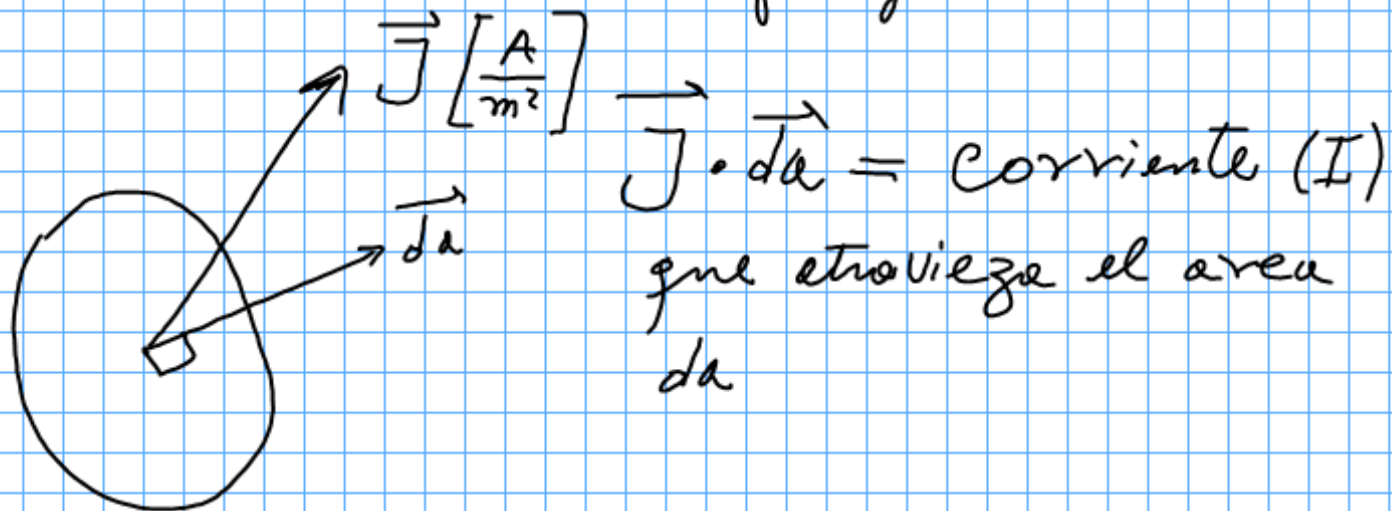
Fza por unidad de largo del conductor

$$|\vec{F}| = \frac{\mu_0}{2\pi} \frac{I I'}{R}$$

Espira

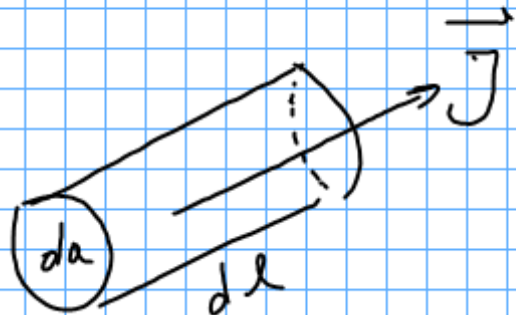


\vec{J} = Vector corriente o flujo de Corriente.



$$\vec{J} \cdot \vec{da} = \text{Corriente (I)}$$

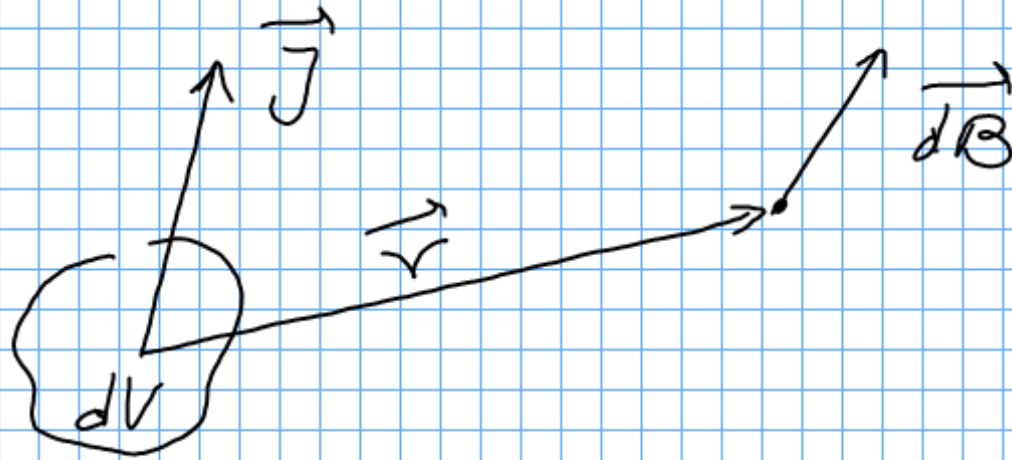
que atravieza el area
 da



$$\begin{aligned} \vec{J} dV &= \vec{J} da dl = J \hat{J} da dl \\ &= J da \hat{J} dl = I d\vec{l} \end{aligned}$$

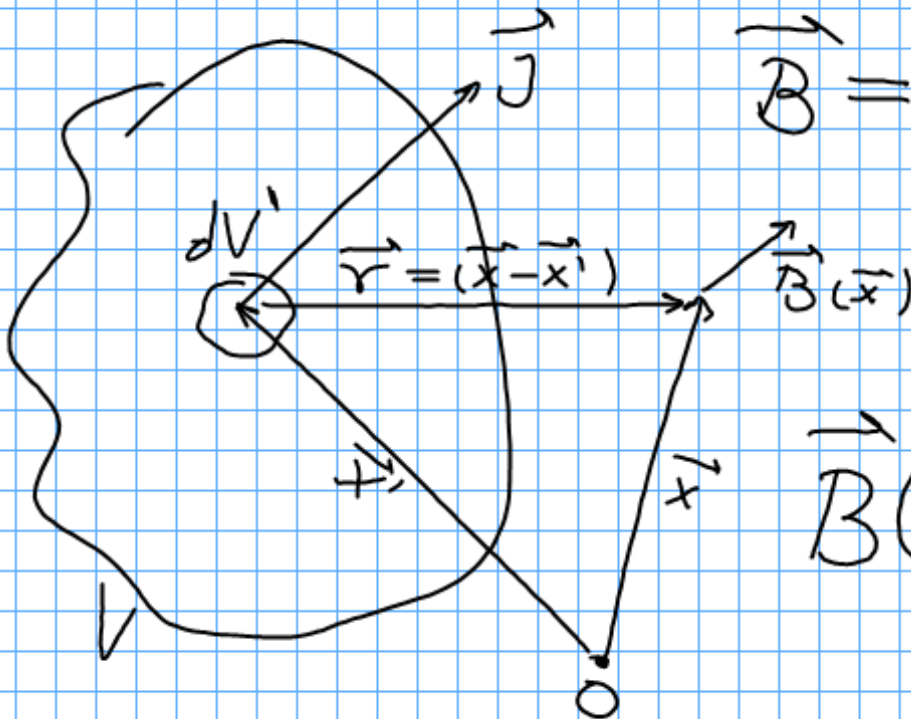
Para flujo de carga Volumetrico

$$I d\vec{l} \longleftrightarrow \vec{J} dV$$



$$d\vec{B} = \frac{\mu_0}{4\pi} \frac{I d\vec{l} \times \hat{r}}{r^2} \longrightarrow \frac{\mu_0}{4\pi} \frac{\vec{J} dV \times \hat{r}}{r^2}$$

$$\vec{B} = \frac{\mu_0}{4\pi} \int_V \frac{\vec{J} \times \hat{r}}{r^2} dV$$

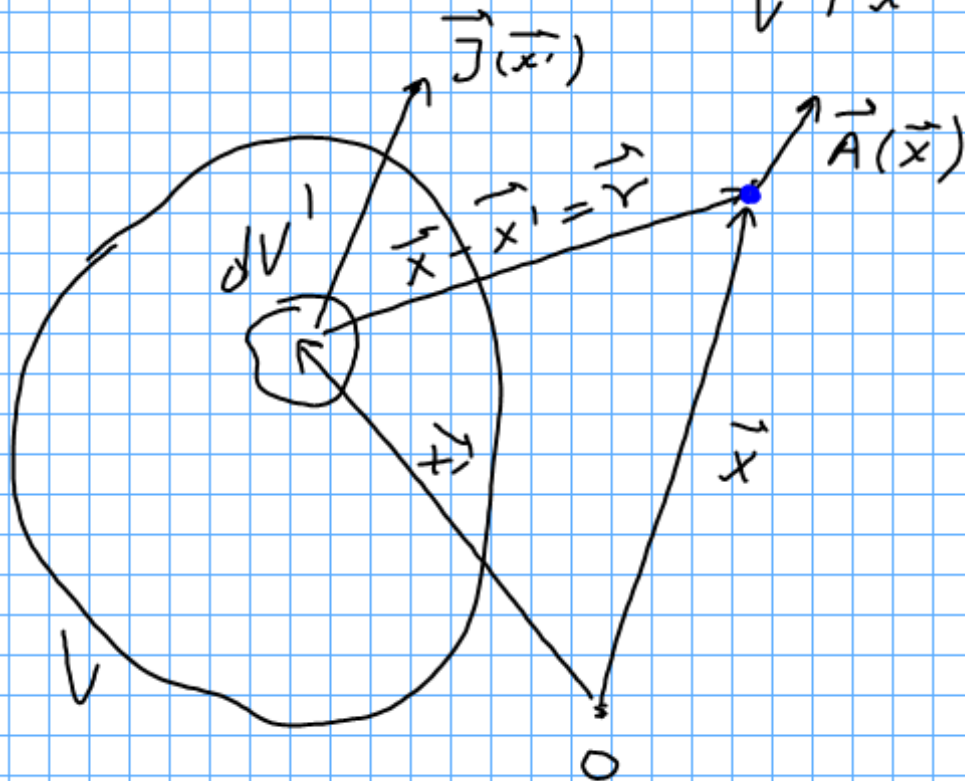


$$\vec{B}(\vec{x}) = \frac{\mu_0}{4\pi} \int_V \frac{\vec{J}(\vec{x}') \times (\vec{x} - \vec{x}')}{|\vec{x} - \vec{x}'|^3} dV'$$

Se puede demostrar que:

$$\vec{B} = \nabla \times \vec{A}, \quad \vec{A} \text{ potencial vector}$$

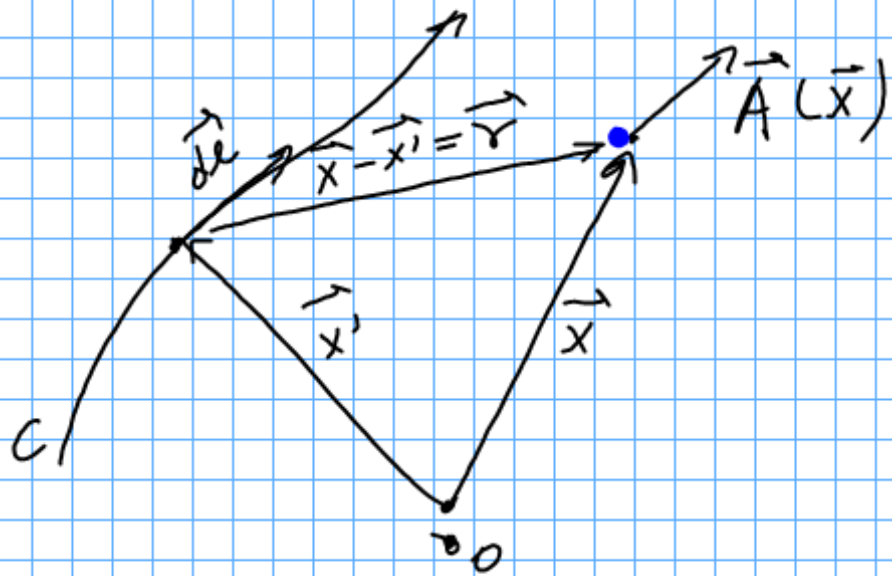
$$\vec{A}(\vec{x}) = \frac{\mu_0}{4\pi} \int_V \frac{\vec{J}(\vec{x}')}{|\vec{x} - \vec{x}'|} dV' = \frac{\mu_0}{4\pi} \int_V \frac{\vec{J}}{r} dV'$$



Si \vec{J} est concentrée en un circuit C ,
 donde circule une corriente I Cte.

$$\vec{J} dV' \rightarrow I d\vec{\ell}$$

$$\vec{A}(\vec{x}) = \frac{\mu_0 I}{4\pi} \int_C \frac{d\vec{\ell}}{|\vec{x} - \vec{x}'|} = \frac{\mu_0 I}{4\pi} \int_C \frac{d\vec{\ell}}{r}$$



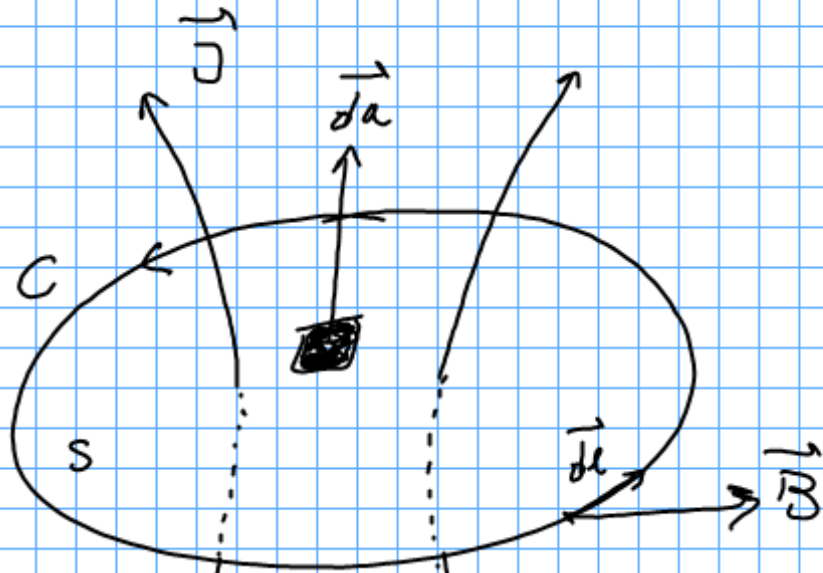
Se tiene entonces:

$$\nabla \cdot \vec{B} = \nabla \cdot (\nabla \times \vec{A}) = 0$$

$$\nabla \cdot \vec{B} = 0 \quad \text{No hay monopolos
magnéticos}$$

$$(\nabla \cdot \vec{g} = -4\pi\epsilon\rho)$$

Ley de Ampere



$$\oint_C \vec{B} \cdot d\vec{l} = \mu_0 I$$

$$I = \int_S \vec{J} \cdot d\vec{a}$$

Por teorema de Stokes:

$$\oint_C \vec{B} \cdot d\vec{l} = \int_S (\nabla \times \vec{B}) \cdot d\vec{a} = \mu_0 \int_S \vec{J} \cdot d\vec{a}$$

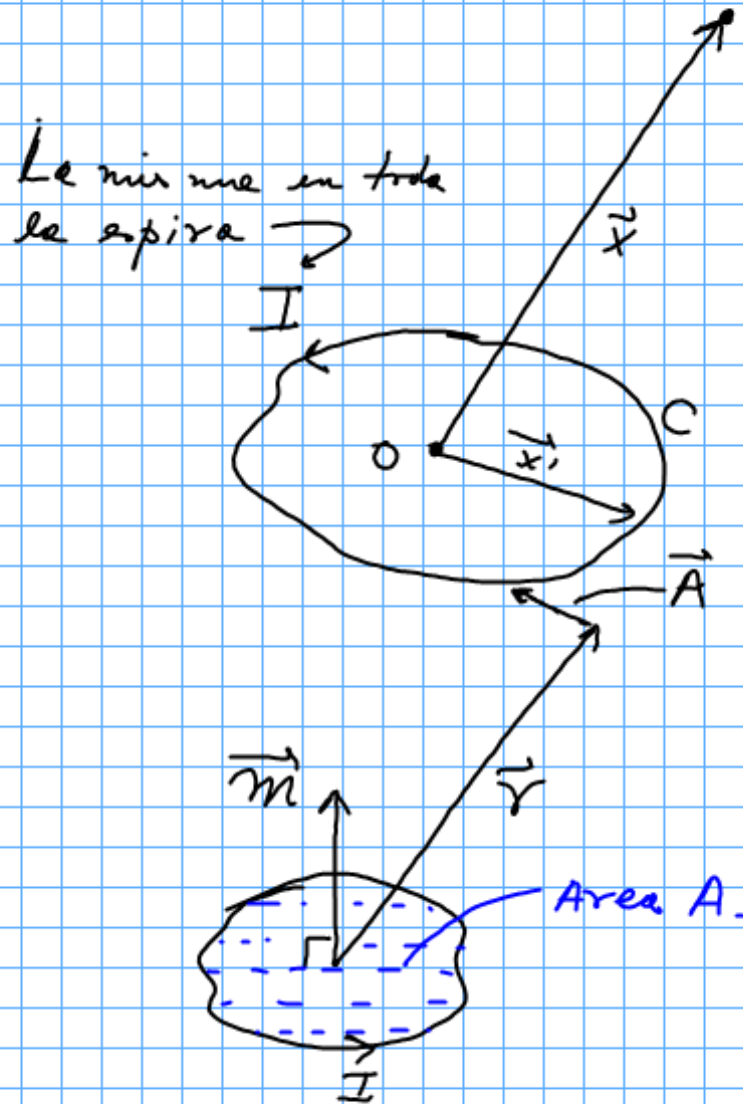
C es una curva arbitraria y \therefore

$$\nabla \times \vec{B} = \mu_0 \vec{J} \quad (\text{Ley de Ampere diferencial})$$

En zonas donde $\vec{J} = 0$, $\nabla \times \vec{B} = 0$, \vec{B} es un campo que puede ser derivado de un potencial escalar (V)

$$\vec{B} = -\nabla V$$

Momento dipolar, Campo de un dipolo (espira) elemental: Imán elemental



$$\vec{A}(\vec{x}) = \frac{\mu_0 I}{4\pi} \oint_C \frac{d\vec{l}}{|\vec{x} - \vec{x}'|}$$

Para una espira elemental (infinitesimal) $|\vec{x}| \gg |\vec{x}'|$

Se puede demostrar:

$$\begin{aligned} \vec{A} &= \frac{\mu_0}{4\pi} \frac{\vec{m} \times \hat{r}}{r^2} \\ &= \frac{\mu_0}{4\pi} \frac{\vec{m} \times \vec{r}}{r^3} \end{aligned}$$

$$|\vec{m}| = I \times A = \text{momento dipolar magnético. [A m}^2\text{]}$$

$$\vec{m} = I \times A \hat{n}, \quad \hat{n} \perp \text{e plano de espira.}$$

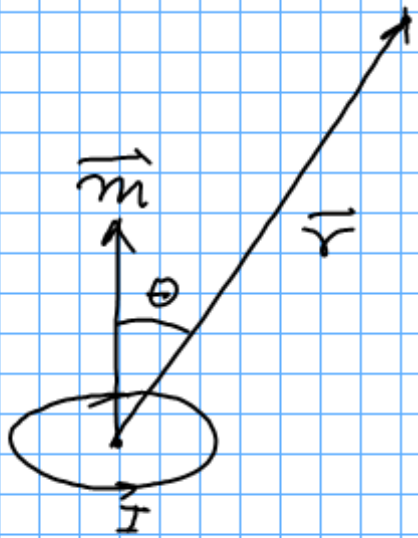
$$\vec{B} = \nabla \times \vec{A} = \frac{\mu_0}{4\pi} \nabla \times \left(\vec{m} \times \frac{\vec{r}}{r^3} \right)$$

Se puede demostrar sin mucha dificultad que:

$$\vec{B} = -\frac{\mu_0}{4\pi} \nabla \left(\vec{m} \cdot \frac{\vec{r}}{r^3} \right)$$

$$\vec{B} = -\nabla V, \quad V = \text{Potencial escalar}$$

$$V = \frac{\mu_0}{4\pi} \vec{m} \cdot \frac{\vec{r}}{r^3} = \frac{\mu_0}{4\pi} \frac{\vec{m} \cdot \hat{r}}{r^2}$$



$$\vec{B} = -\nabla V$$

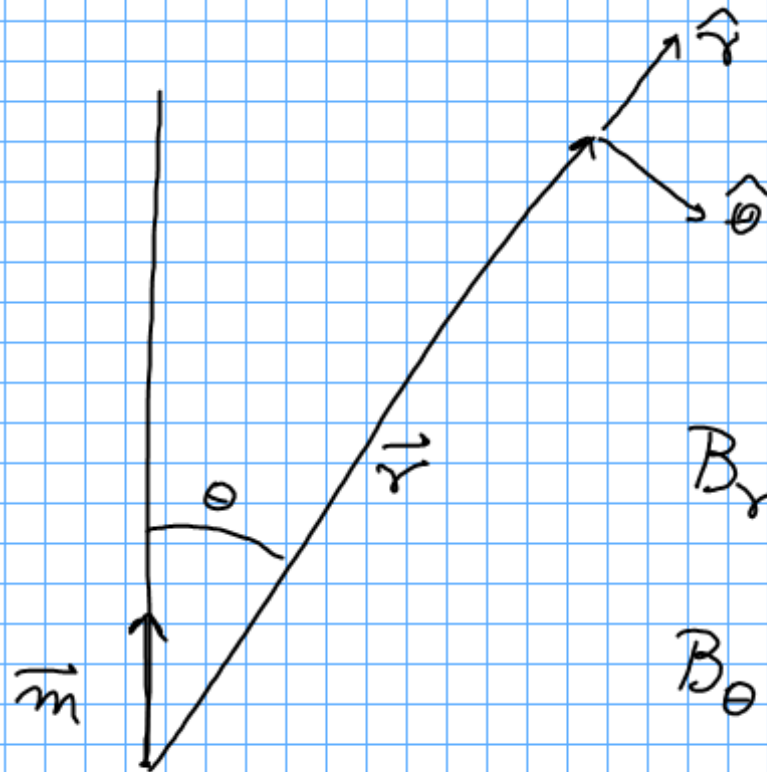
$$V = \frac{\mu_0}{4\pi} \frac{\vec{m} \cdot \hat{r}}{r^2}, \quad \vec{m} \cdot \hat{r} = m \cos\theta$$

$$V = \frac{\mu_0}{4\pi} \frac{m \cos\theta}{r^2} = V(r, \theta)$$

Se tiene:

$$\vec{B} = \frac{\mu_0}{4\pi} \left[3(\hat{m} \cdot \hat{r})\hat{r} - \hat{m} \right] \frac{m}{r^3}$$

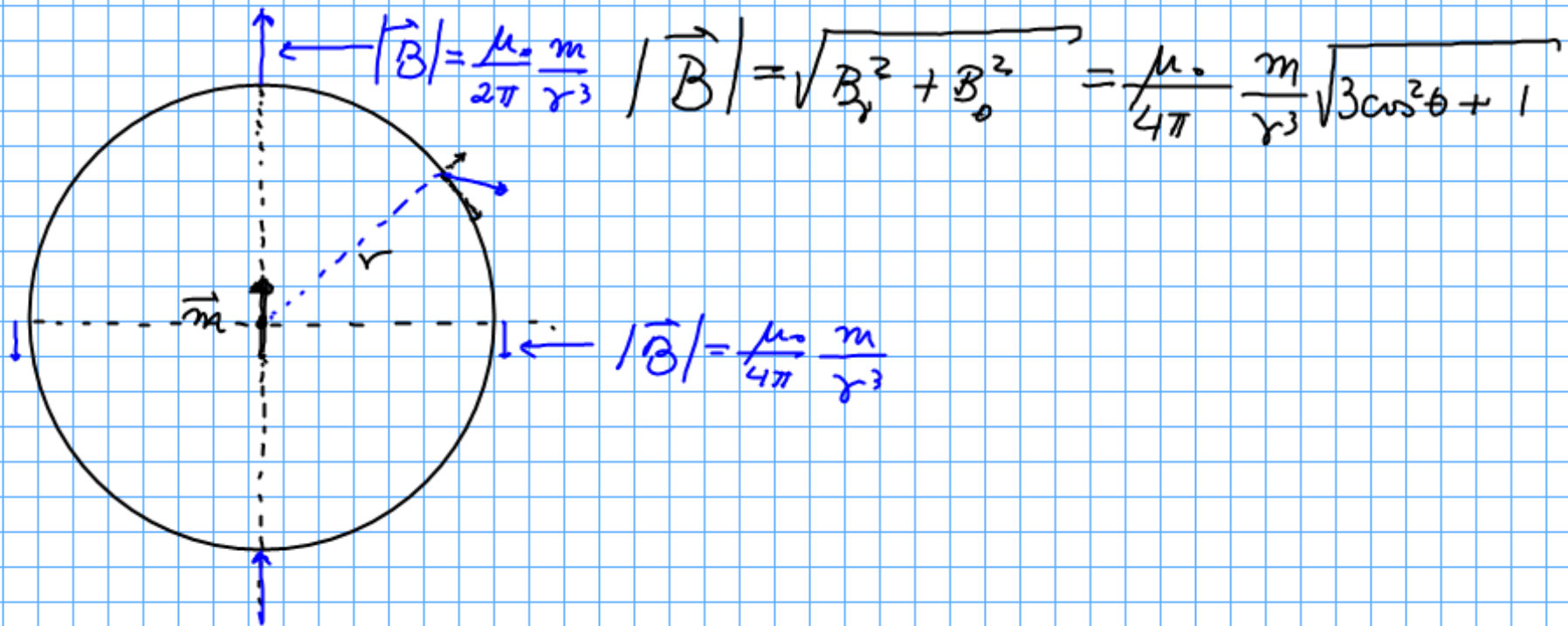
$$= \frac{\mu_0 m}{4\pi r^3} \left[3\cos\theta \hat{r} - \hat{m} \right]$$



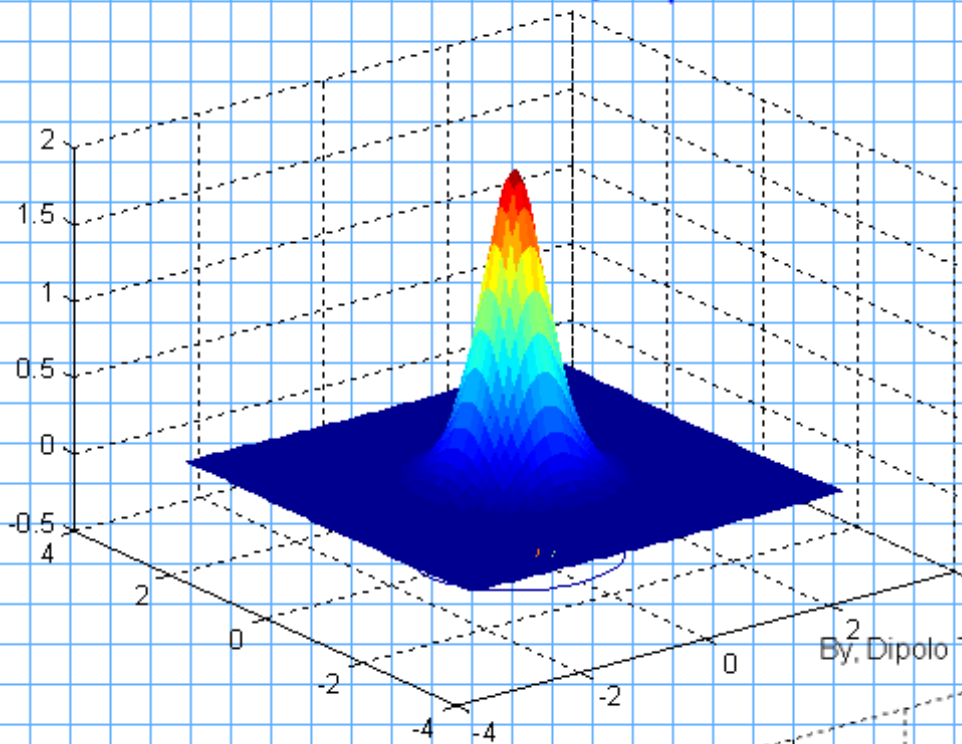
$$V = \frac{\mu_0}{4\pi} \frac{m \cos\theta}{r^2} = V(r, \theta)$$

$$B_r = -\frac{\partial V}{\partial r} = 2 \frac{\mu_0}{4\pi} \frac{m \cos\theta}{r^3}$$

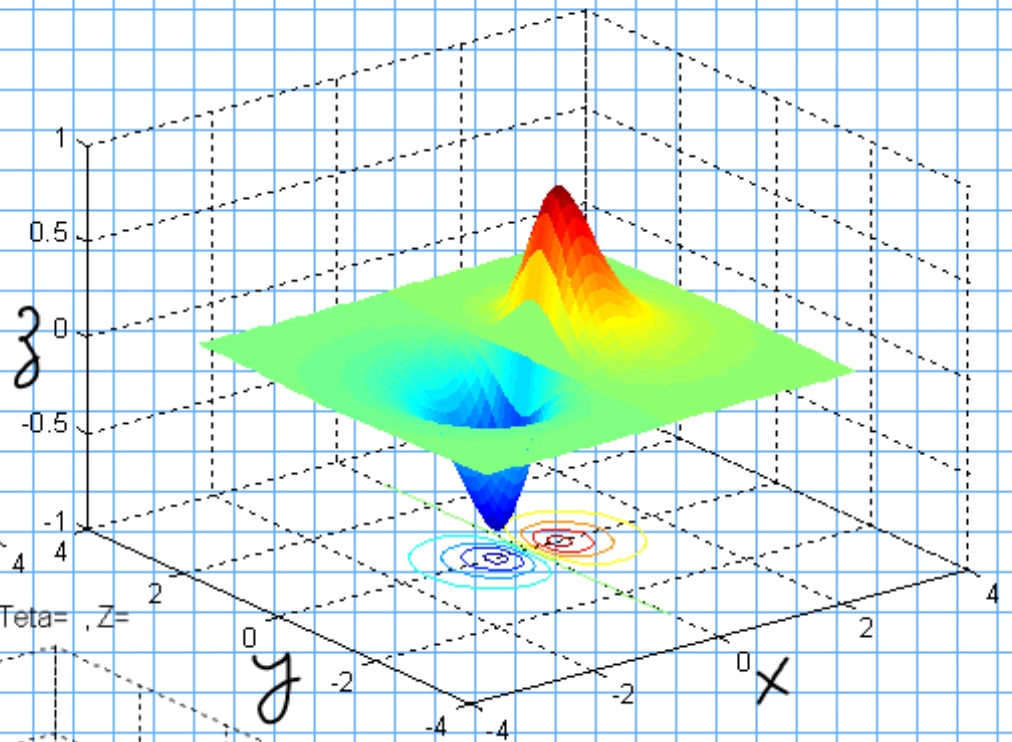
$$B_\theta = -\frac{1}{r} \frac{\partial V}{\partial \theta} = \frac{\mu_0}{4\pi} \frac{m \sin\theta}{r^3}$$



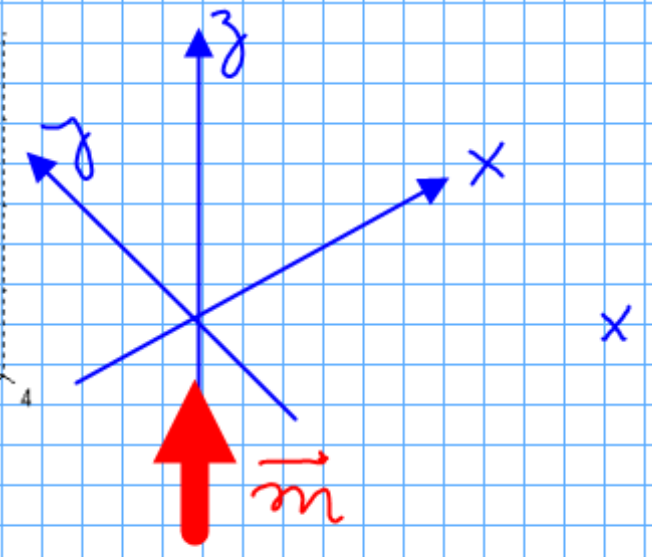
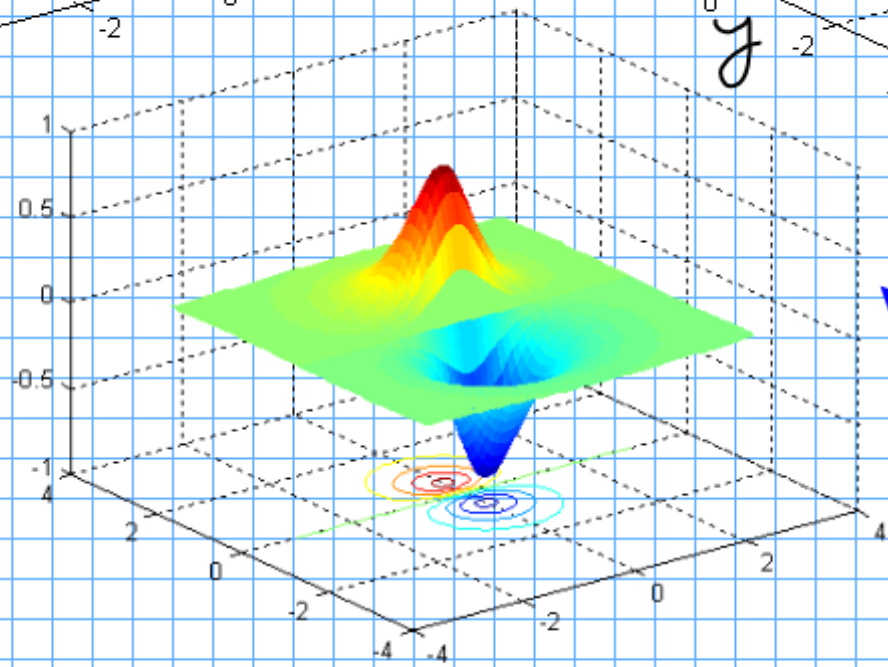
Bz, Dipolo Teta=0, Z=1



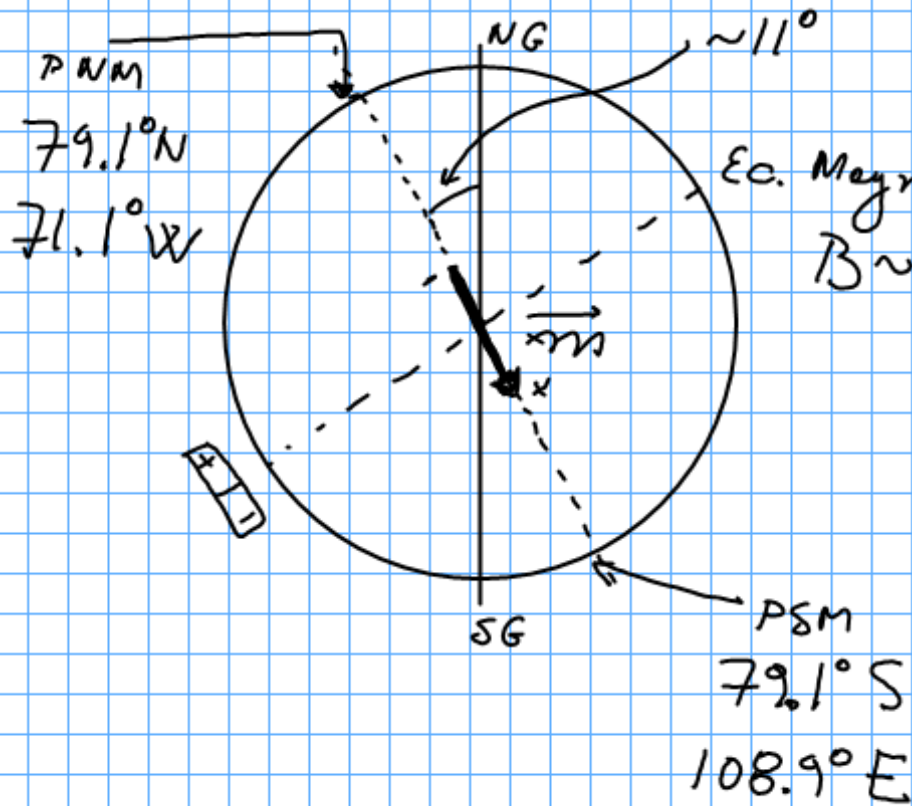
Bx, Dipolo Teta=, Z=



By, Dipolo Teta=, Z=



Dipolo Magnético Terrestre



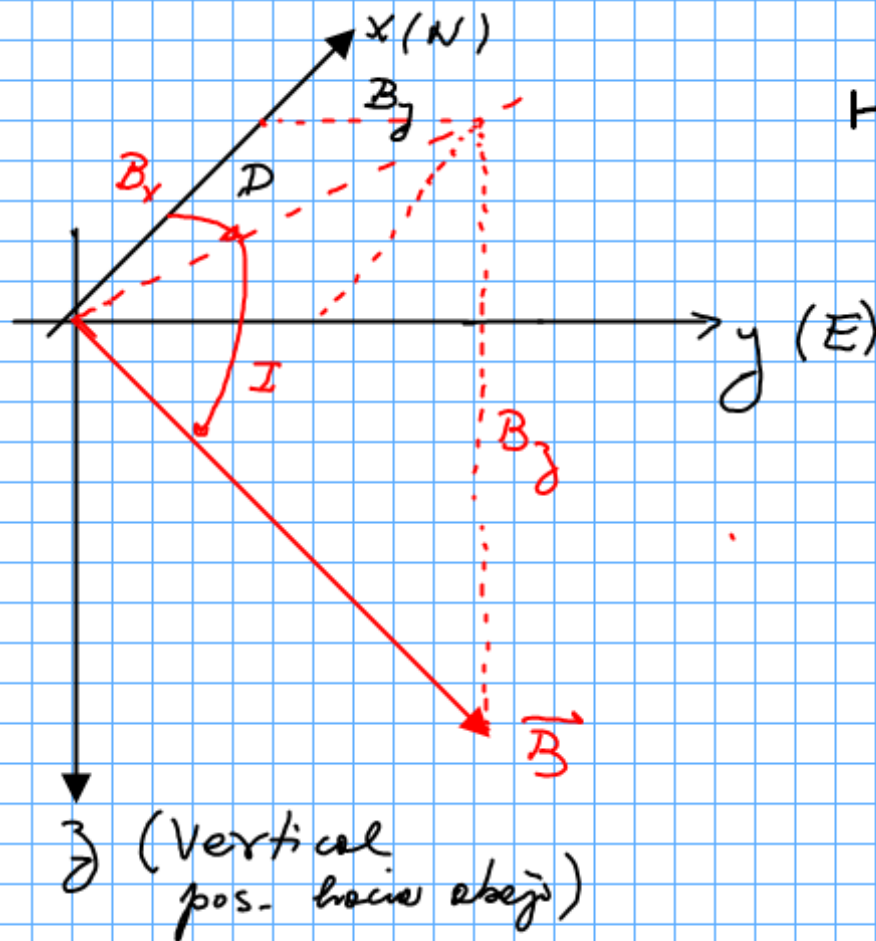
$$B \sim 31000 \text{ nT} = \frac{\mu_0}{4\pi} \frac{m}{R_T^3}, \quad R_T \sim 6370 \text{ km}$$

$$m = B R_T^3 \frac{4\pi}{\mu_0}$$

$$= 3.1 \times 10^{-5} \times 6.37^3 \times 10^{18} \times 10^7$$

$$m \sim 8 \times 10^{22} \text{ A m}^2$$

Elementos del Campo Magnético Terrestre



H = Campo horizontal

$$= \sqrt{B_x^2 + B_y^2}$$

I = Inclinación

$$= \tan^{-1} \left(\frac{B_z}{H} \right)$$

D = Declinación

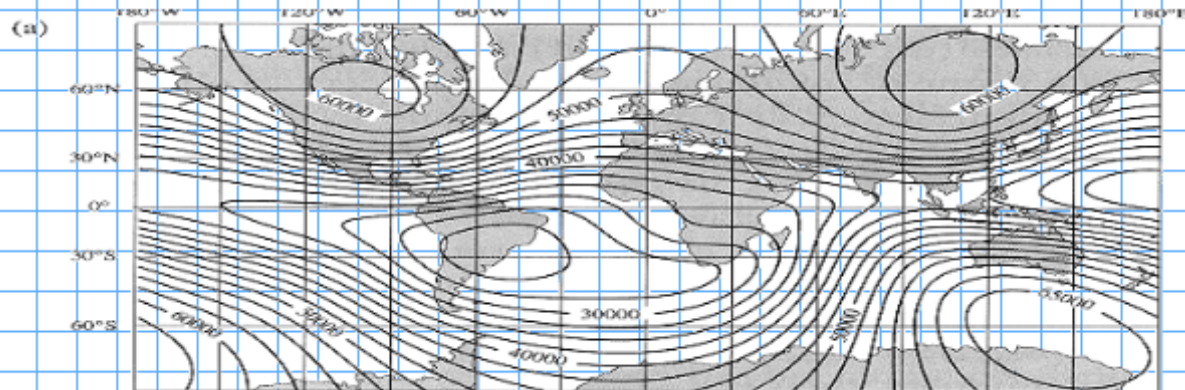
$$= \tan^{-1} \left(\frac{B_y}{B_x} \right)$$

$$T = \text{Campo total} = |\vec{B}| = \sqrt{B_x^2 + B_y^2 + B_z^2}$$

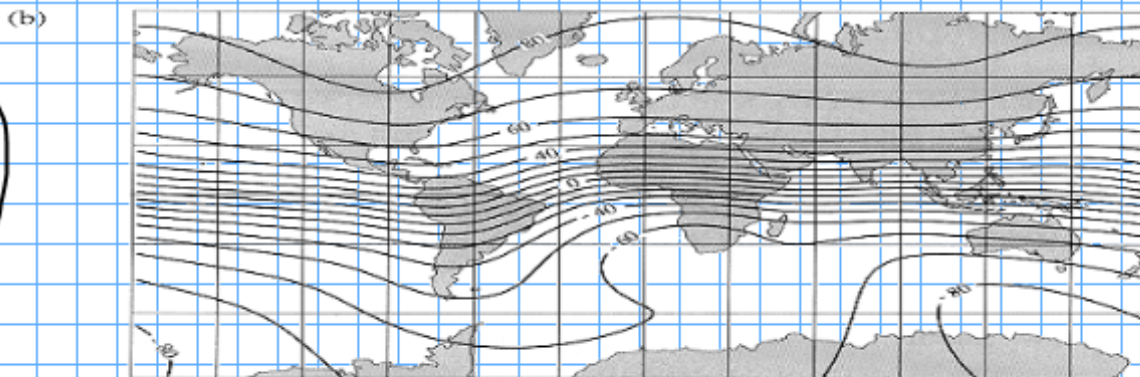
IGRF, International Geomagnetic Reference Field.

www.ngdc.noaa.gov/IAGA/vmod/igrf.html

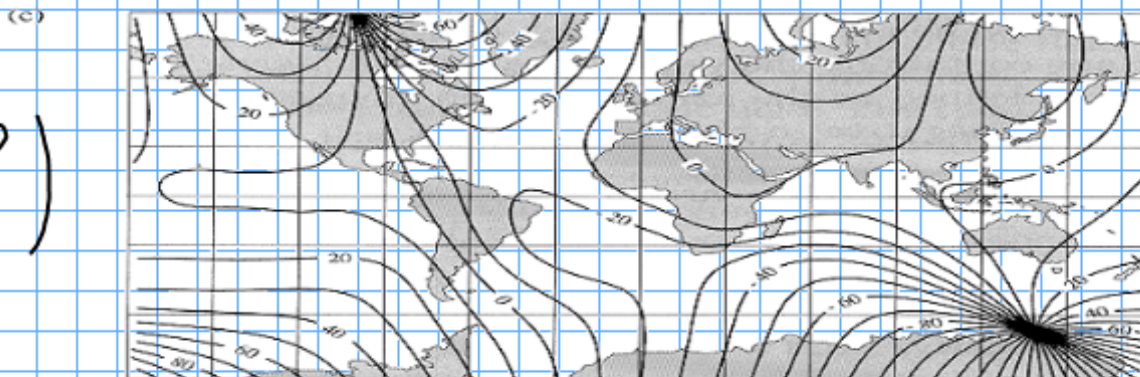
T (nT)



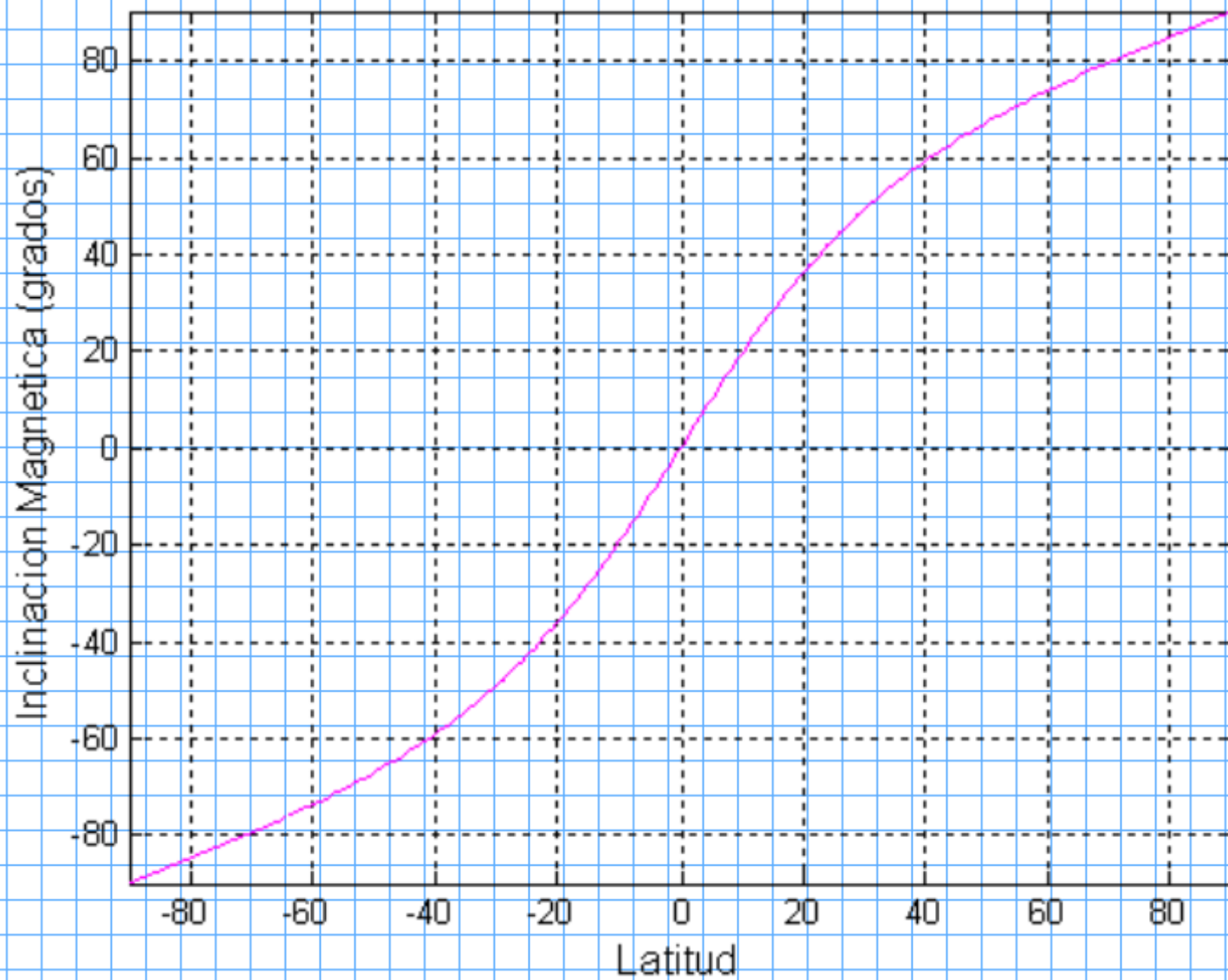
I ($^{\circ}$)



D ($^{\circ}$)



Dipolo Terrestre Axial



Cuerpos Magnetizados

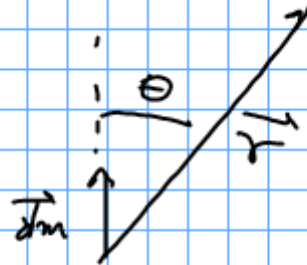
 \vec{M}

= Magnetización: Momento dipolar por unidad de volumen



$d\vec{m} = \vec{M} dV$: Momento magnético en dV

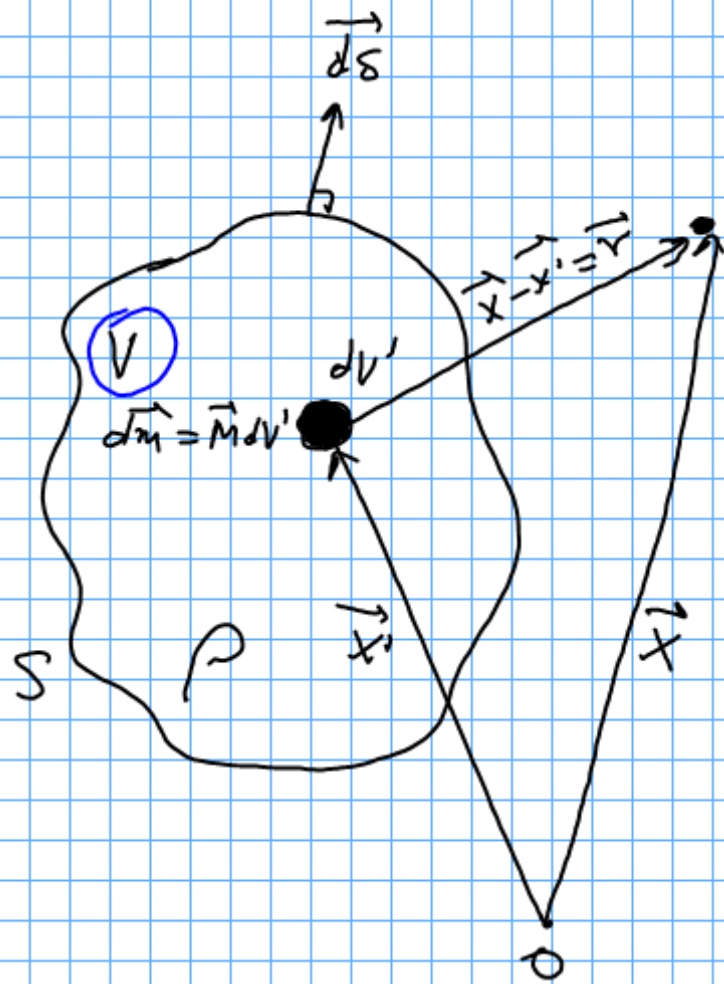
$$[A \cdot m^2] \quad \left[\frac{A}{m} \right]$$



$$V = \frac{\mu_0}{4\pi} \frac{dm \cdot \vec{r}}{r^3}$$

$$= \frac{\mu_0}{4\pi} \frac{dm \cos \theta}{r^2}$$

$$\vec{dB} = -\nabla V$$



$$V(\vec{x}) = \frac{\mu_0}{4\pi} \int \frac{\vec{M} \cdot (\vec{x} - \vec{x}')}{|\vec{x} - \vec{x}'|^3} dV'$$

Si \vec{M} constante:

$$V(\vec{x}) = -\frac{\mu_0}{4\pi} \vec{M} \cdot \nabla \int \frac{dV'}{|\vec{x} - \vec{x}'|}$$

$$\nabla \left(\frac{1}{|\vec{x} - \vec{x}'|} \right) = -\frac{\vec{x} - \vec{x}'}{|\vec{x} - \vec{x}'|^3}$$

$$V(\vec{x}) = -\frac{\mu_0}{4\pi} \vec{M} \cdot \nabla \left(-\frac{U}{G\rho} \right)$$

donde

$$U = -G\rho \int_V \frac{dV'}{|\vec{x} - \vec{x}'|}$$

es el potencial gravitatorio del volumen V , si este se considera lleno de material de densidad constante ρ

$$\vec{V} = \frac{\mu_0}{4\pi G\rho} \vec{M} \cdot \nabla U = -\frac{\mu_0}{4\pi G\rho} \vec{M} \cdot \vec{g}$$

Relación de Poisson

$$\text{Sea } \vec{M} = M \hat{\alpha} = M(l, m, n)$$

$$\begin{aligned} \vec{M} \cdot \nabla U &= M \hat{\alpha} \cdot \nabla U = M(l, m, n) \cdot \left(\frac{\partial U}{\partial x}, \frac{\partial U}{\partial y}, \frac{\partial U}{\partial z} \right) \\ &= M \left(l \frac{\partial U}{\partial x} + m \frac{\partial U}{\partial y} + n \frac{\partial U}{\partial z} \right) \\ &= M \frac{\partial U}{\partial \alpha} \end{aligned}$$

$$\frac{\partial}{\partial \alpha} = l \frac{\partial}{\partial x} + m \frac{\partial}{\partial y} + n \frac{\partial}{\partial z} = \text{derivada direccional en el sentido } \hat{\alpha}$$

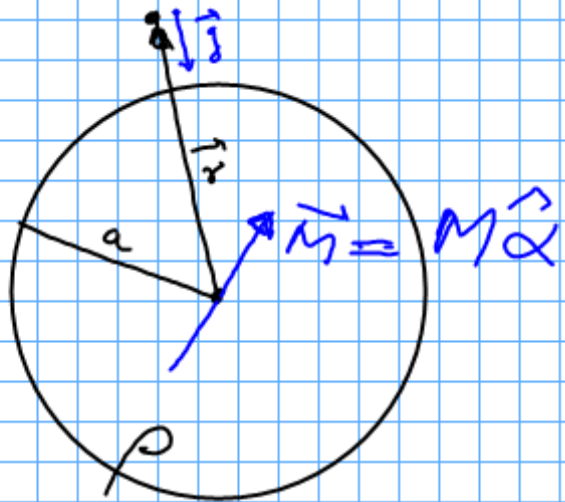
$$\therefore V = \frac{\mu_0}{4\pi G \rho} M \frac{\partial U}{\partial \alpha} \quad (\text{Rel. Poisson})$$

Entonces

$$\vec{B} = -\nabla V = \frac{\mu_0}{4\pi\rho G} M \frac{\partial(-\nabla U)}{\partial \alpha} = \frac{\mu_0}{4\pi\rho G} \frac{\partial \vec{g}}{\partial \alpha}$$

Ejemplos de uso de relación de Poisson

1- Esfera uniformemente magnetizada

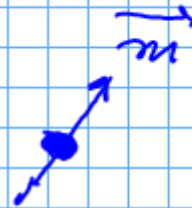
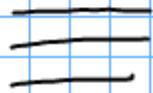
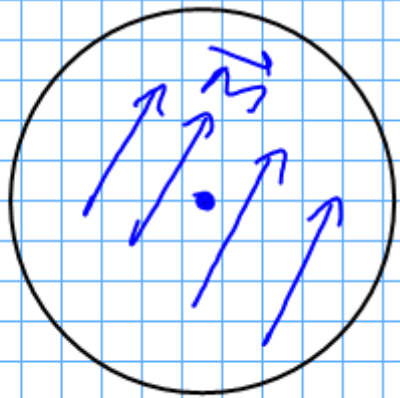


$$V = \frac{\mu_0}{4\pi} \frac{\vec{M} \cdot \nabla U}{\rho G} = -\frac{\mu_0}{4\pi} \frac{\vec{M} \cdot \vec{g}}{\rho G}$$

$$\vec{g} = -G\rho \frac{4}{3}\pi a^3 \frac{\hat{r}}{r^2}$$

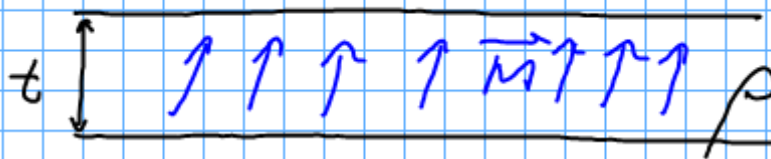
$$V = \frac{\mu_0}{4\pi} \frac{4\pi a^3 M}{3} \frac{\hat{\alpha} \cdot \hat{r}}{r^2}$$

$$= \frac{\mu_0}{4\pi} \frac{\vec{m} \cdot \hat{r}}{r^2}, \quad \vec{m} = \frac{4\pi a^3}{3} \vec{M}$$



2- Placa infinita

$$\vec{g} = -2\pi G \rho t \hat{z}$$

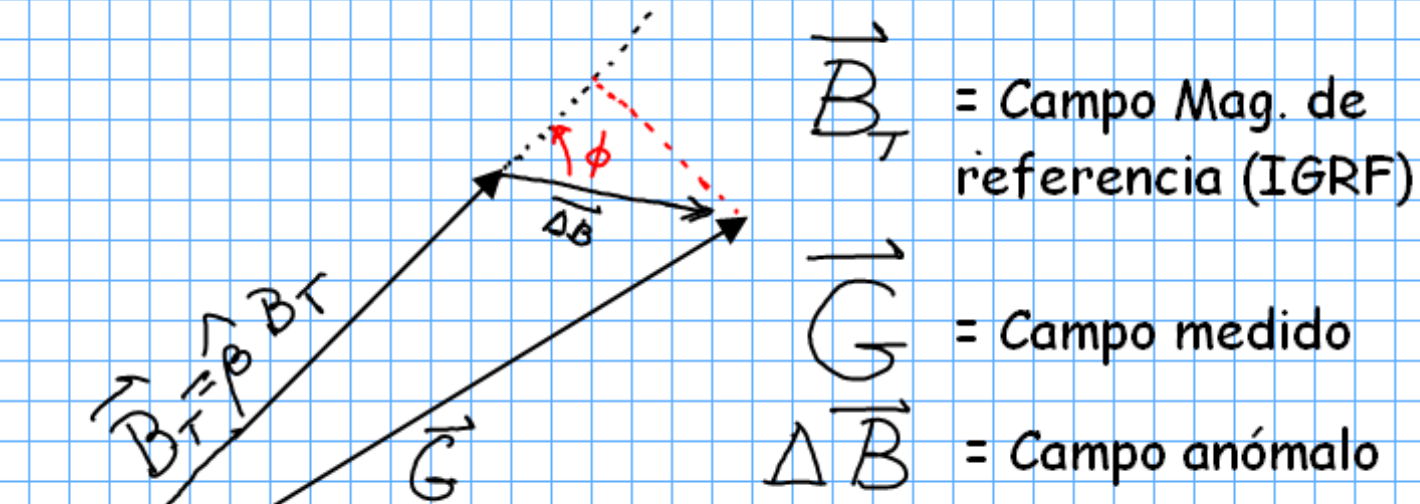


$$V = \frac{\mu_0}{4\pi} \frac{\vec{M} \cdot \hat{z}}{\rho G} 2\pi G \rho t = \frac{\mu_0 t}{2} M_z = Gk.$$

$$\therefore \vec{B} = -\nabla V = 0$$

El campo magnético de una placa infinita uniformemente magnetizada es nulo.

Anomalía de Campo Total (A_T)



$$A_T = |\vec{G}| - |\vec{B}_T|$$

En general $|\Delta \vec{B}| \ll |\vec{B}_T| \therefore |\vec{G}| \sim |\vec{B}_T| + |\Delta \vec{B}| \cos \phi$

$$A_T \simeq |\Delta \vec{B}| \cos \phi = \hat{\beta} \cdot \Delta \vec{B}, \quad \hat{\beta} = (\ell', m', n')$$

Suponiendo ΔB lo produce un cuerpo uniformemente magnetizado: $\vec{M} = \hat{\alpha} M$, $\hat{\alpha} = (l, m, n)$



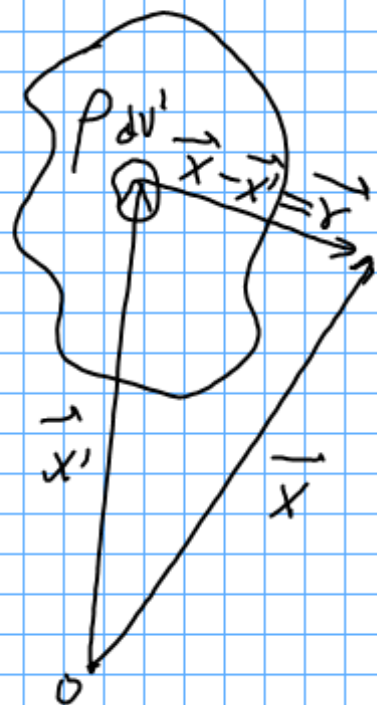
$$V = \frac{\mu_0 M}{4\pi\rho G} \frac{\partial U}{\partial \alpha} = \frac{\mu_0 M}{4\pi\rho G} \left[l \frac{\partial U}{\partial x} + m \frac{\partial U}{\partial y} + n \frac{\partial U}{\partial z} \right]$$

$$\Delta \vec{B} = -\nabla V = -\frac{\mu_0 M}{4\pi\rho G} \nabla \left(\frac{\partial U}{\partial \alpha} \right)$$

$$\therefore A_T = -\frac{\mu_0 M}{4\pi\rho G} \hat{\beta} \cdot \nabla \left(\frac{\partial U}{\partial \alpha} \right)$$

$$= -\frac{\mu_0 M}{4\pi\rho G} \frac{\partial^2 U}{\partial \rho \partial \alpha}, \quad \frac{\partial}{\partial \rho} = l' \frac{\partial}{\partial x} + m' \frac{\partial}{\partial y} + n' \frac{\partial}{\partial z}$$

$$A_T = -\frac{\mu_0 M}{4\pi\rho G} \left(l' \frac{\partial}{\partial x} + m' \frac{\partial}{\partial y} + n' \frac{\partial}{\partial z} \right) \left(l \frac{\partial}{\partial x} + m \frac{\partial}{\partial y} + n \frac{\partial}{\partial z} \right) U$$



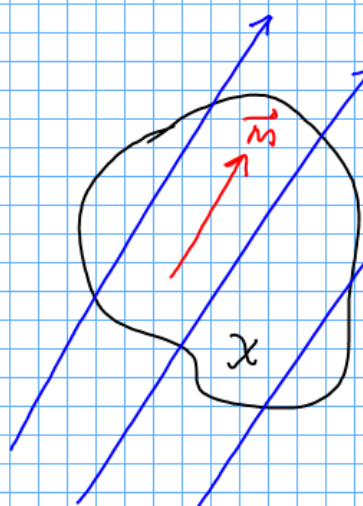
$$-\frac{U}{\rho G} = \int_V \frac{dv'}{|\vec{x} - \vec{x}'|} = \int_V \frac{dv'}{r} = \phi$$

$$A_T = \frac{\mu_0}{4\pi} M \left(l' \frac{\partial}{\partial x} + m' \frac{\partial}{\partial y} + n' \frac{\partial}{\partial z} \right) \left(l \frac{\partial}{\partial x} + m \frac{\partial}{\partial y} + n \frac{\partial}{\partial z} \right) \phi$$

\uparrow
 CAMPO DE
 REFERENCIA.

\uparrow
 MAGNETIZACIÓN

Magnetización Inducida



$$\vec{B}_0 = B_0 \hat{\alpha}$$

$$\vec{M} \sim \chi \frac{\vec{B}_0}{\mu_0} = \frac{\chi B_0}{\mu_0} \hat{\alpha}$$

χ = Susceptibilidad magnética (SI)

$$\chi \ll 1$$

$$\text{Si } \vec{B}_0 = \vec{B}_T \quad \hat{\alpha} = \hat{\beta}, \quad M = \frac{\chi B_0}{\mu_0}$$

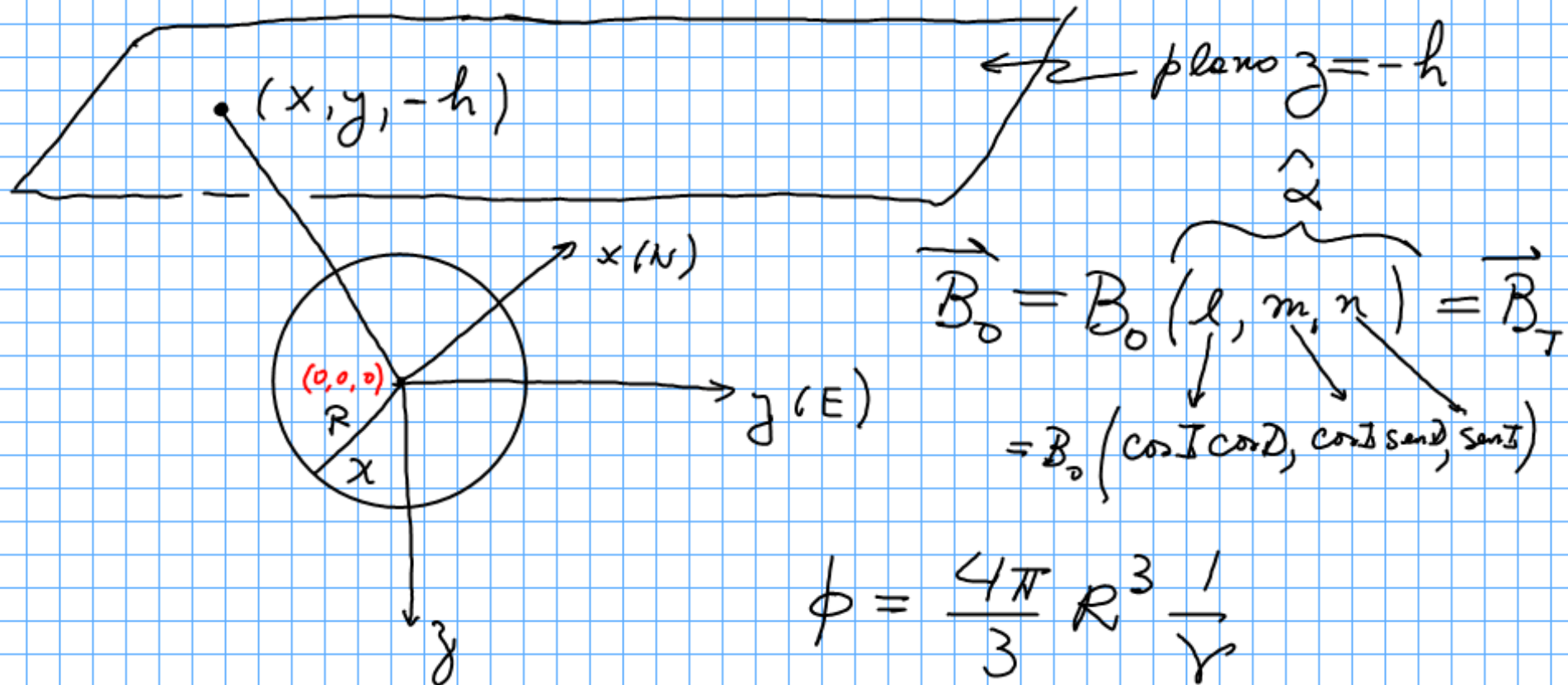
$$\begin{aligned} A_T &= \frac{\mu_0}{4\pi} \frac{\chi B_0}{\mu_0} \frac{\partial^2 \phi}{\partial \alpha^2} = \frac{\chi}{4\pi} B_0 \frac{\partial^2 \phi}{\partial \alpha^2} \\ &= \chi_{cgs} B_0 \frac{\partial^2 \phi}{\partial \alpha^2}, \quad \chi_{cgs} = \frac{\chi}{4\pi} = \chi_{emu} \end{aligned}$$

Mediciones de susceptibilidad magnética en laboratorio

ROCA	$\chi_{cgs} \times 10^6$
Dolomita	8
Caliza	23
Arenisca	32
Pizarra	52
Metamórfica	350
Ignea ácida	650
Ignea básica	2600

$$\chi = \chi_{SI} = 4\pi \chi_{cgs}$$

Esfera Magnetizada en Campo Terrestre



$$A_T = \chi_{\text{eff}} B_0 \frac{4\pi}{3} R^3 \frac{\partial^3}{\partial \alpha^2} \left(\frac{1}{r} \right), \quad r = \sqrt{x^2 + y^2 + z^2}$$

$$\frac{\partial}{\partial \alpha} \left(\frac{1}{r} \right) = - \frac{l x + m y + n z}{r^3}$$

$$A_T = -\chi_{emu} B_0 \frac{4\pi}{3} R^3 \frac{\partial}{\partial \alpha} \left(\frac{l x + m y + n z}{r^3} \right)$$

$$= -\chi_{emu} B_0 \frac{4\pi}{3} R^3 \left[(l x + m y + n z) \frac{\partial r^{-3}}{\partial \alpha} + r^3 \frac{\partial}{\partial \alpha} (l x + m y + n z) \right]$$

$$= -\chi_{emu} B_0 \frac{4\pi}{3} R^3 \left[-\frac{3(l x + m y + n z)^2}{r^5} + \frac{l^2 + m^2 + n^2}{r^3} \right]$$

$$l^2 + m^2 + n^2 = 1, \quad l x + m y + n z = \vec{r} \cdot \hat{\alpha}$$

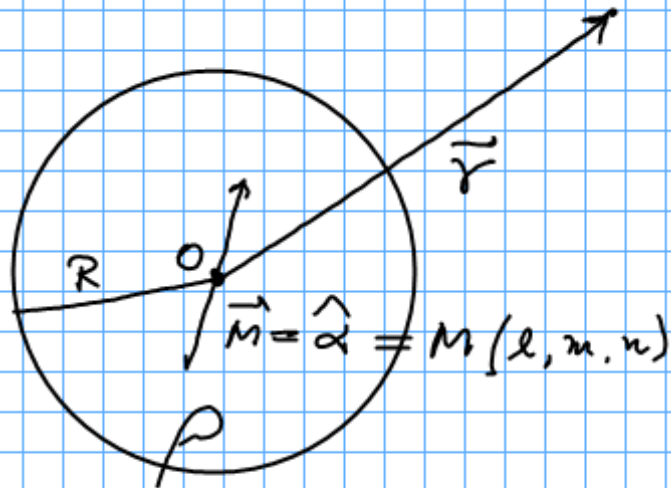
$$A_T = \chi_{emu} B_0 \frac{4\pi}{3} \left(\frac{R}{r} \right)^3 \left[3(\hat{r} \cdot \hat{\alpha})^2 - 1 \right]$$

Sobre la superficie ($z = -h$)

$$\vec{r} = (x, y, -h), \quad r = \sqrt{x^2 + y^2 + h^2}$$

$$\hat{r} = \frac{\vec{r}}{r} = \frac{(x, y, -h)}{\sqrt{x^2 + y^2 + h^2}}$$

Esfera Magnetizada : Caso general



$$\begin{aligned}\vec{B}_T &= B_T \hat{\rho} \\ &= B_T (l', m', n')\end{aligned}$$

Relación de Poisson: $V = -\frac{\mu_0}{4\pi} \frac{M}{\rho G} \hat{\alpha} \cdot \vec{g}, \vec{B} = -\nabla V$

$$\begin{aligned}\vec{g} &= -\frac{G\rho V}{r^3} \hat{\alpha}, \quad V = \frac{\mu_0}{4\pi} MV \frac{\hat{\alpha} \cdot \vec{r}}{r^3} \\ &= \frac{\mu_0}{4\pi} MV \left[\frac{lx + my + nz}{r^3} \right]\end{aligned}$$

$$\vec{B} = -\nabla V = -\frac{\mu_0}{4\pi} MV \left[\hat{\alpha} \cdot \vec{r} \nabla \left(\frac{1}{r^3} \right) + \nabla (\hat{\alpha} \cdot \vec{r}) \frac{1}{r^3} \right]$$

$$= \frac{\mu_0}{4\pi} MV \frac{1}{r^3} \left[3 (\hat{\alpha} \cdot \vec{r}) \hat{r} - \hat{\alpha} \right]$$

$$\vec{B} = \frac{\mu_0}{4\pi} M \frac{4\pi}{3} \left(\frac{R}{r} \right)^3 \left[3 (\hat{\alpha} \cdot \vec{r}) \hat{r} - \hat{\alpha} \right]$$

$$A_T = \hat{\beta} \cdot \vec{B} = \frac{\mu_0 M}{3} \left(\frac{R}{r} \right)^3 \left[3 (\hat{\alpha} \cdot \vec{r}) (\hat{\beta} \cdot \vec{r}) - \hat{\beta} \cdot \hat{\alpha} \right]$$

Si la magnetización de la esfera es, o fue producida por un campo externo $\vec{B}_0 = B_0 \hat{\alpha}$:

$$M = \chi \frac{B_0}{\mu_0} = 4\pi \chi_{emu} \frac{B_0}{\mu_0}$$

$$A_T = \frac{4\pi}{3} \chi_{emu} B_0 \left(\frac{R}{r}\right)^3 \left[3(\hat{\alpha} \cdot \hat{r})(\hat{\beta} \cdot \hat{r}) - \hat{\alpha} \cdot \hat{\beta} \right]$$

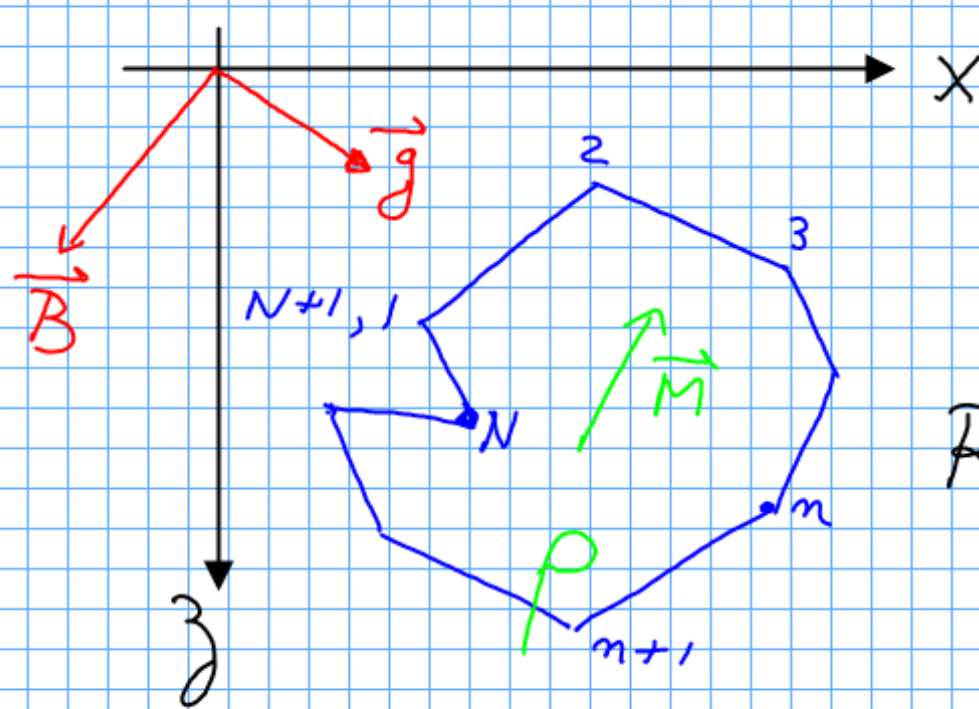
En el caso común de magnetización inducida por el campo de referencia:

$$\vec{B}_0 = \vec{B}_T, \quad \hat{\alpha} = \hat{\beta}, \quad B_0 = B_T$$

$$\therefore A_T = \frac{4\pi}{3} \chi_{emu} B_0 \left(\frac{R}{r}\right)^3 \left[3(\hat{\alpha} \cdot \hat{r})^2 - 1 \right]$$

Modelación magnética 2D

I.J. Won & M. Bevis, Computing the gravitational and magnetic anomalies due to a polygon: Algorithms and Fortran subroutines, *Geophysics* 52, pp 232-238, 1987.



$$\vec{g} = (g_x, g_z)$$

$$\vec{B} = (B_x, B_z)$$

Relación de Poisson:

$$V = \frac{\mu_0}{4\pi\rho G} M \frac{\partial U}{\partial \alpha}$$

$$\vec{M} = M \hat{\alpha} = M (l, m, n), \quad \frac{\partial}{\partial \alpha} = l \frac{\partial}{\partial x} + m \frac{\partial}{\partial y} + n \frac{\partial}{\partial z}$$

$$\vec{B} = -\nabla V, \quad \vec{g} = -\nabla U$$

$$\vec{B} = -\nabla V = \frac{\mu_0}{4\pi r^3} M \frac{\partial}{\partial \alpha} (-\nabla U)$$

$$= \frac{\mu_0}{4\pi r^3} M \frac{\partial \vec{g}}{\partial \alpha}$$

\therefore

$$B_x = \frac{\mu_0}{4\pi r^3} M \frac{\partial g_x}{\partial \alpha}$$

$$B_z = \frac{\mu_0}{4\pi r^3} M \frac{\partial g_z}{\partial \alpha}$$

$$g_z = 2G\rho \sum_{n=1}^N Z_n$$

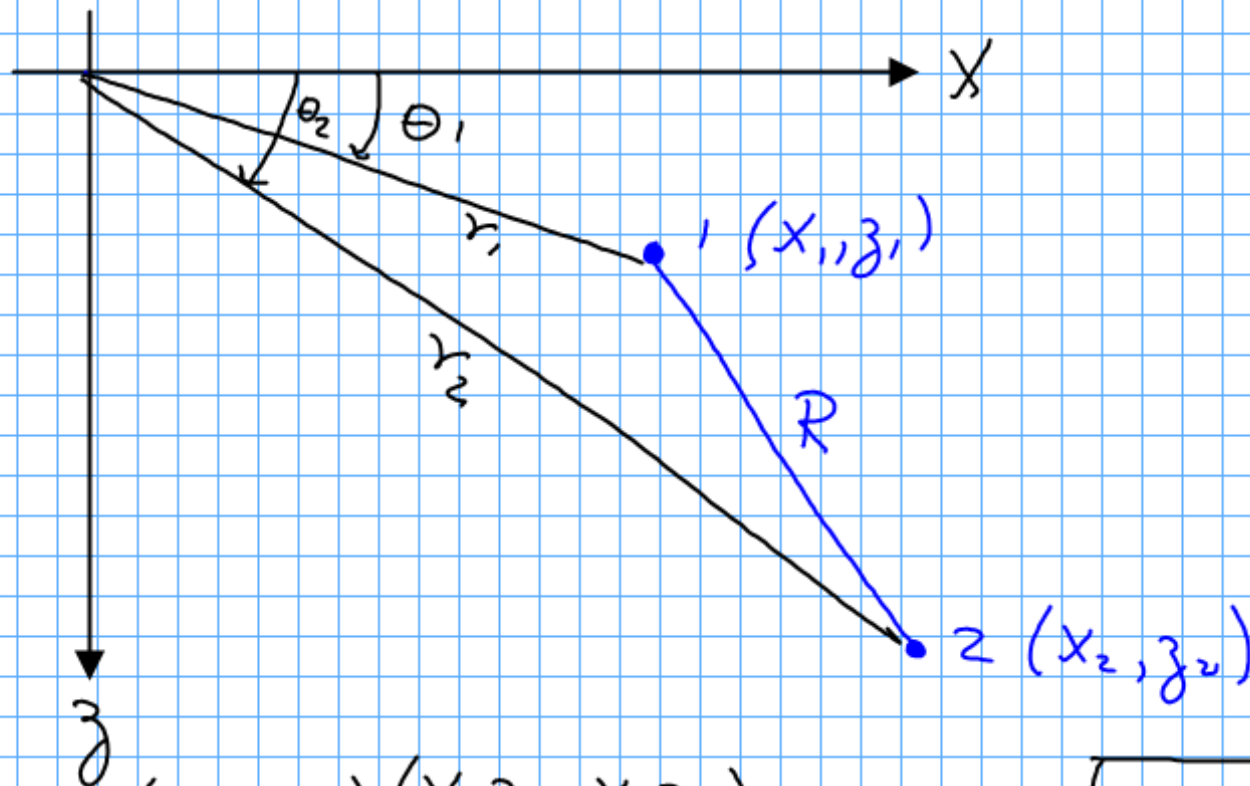
$$g_x = 2G\rho \sum_{n=1}^N X_n$$

Z_n, X_n dependen de los vertices $n, n+1$.

Sin perdida de generalidad para estos vertices sucesivos usamos indices 1 y 2:

$$Z = A \left[(\theta_1 - \theta_2) + B \ln \frac{r_2}{r_1} \right]$$

$$X = A \left[-(\theta_1 - \theta_2) B + \ln \frac{r_2}{r_1} \right]$$

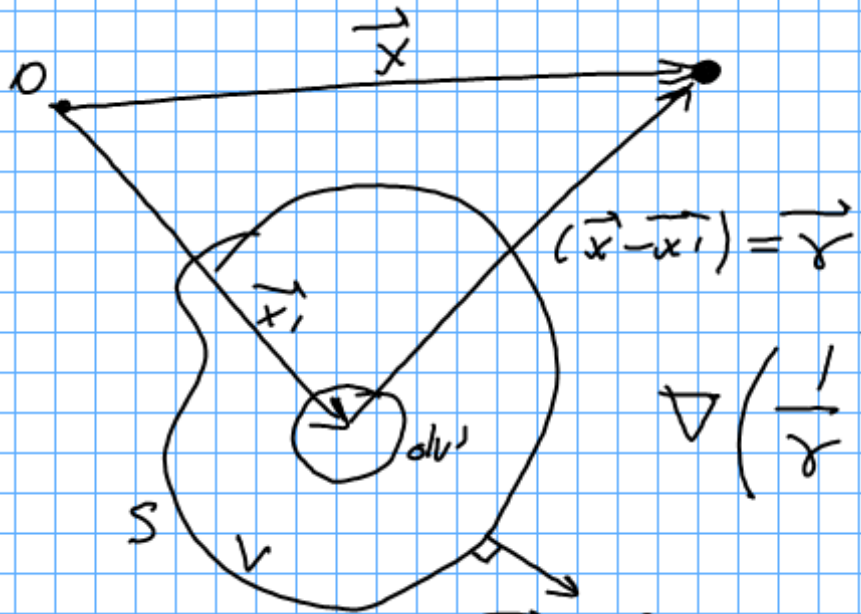


$$A = \frac{(x_2 - x_1)(x_1 z_2 - x_2 z_1)}{R^2}, \quad R = \sqrt{(x_2 - x_1)^2 + (z_2 - z_1)^2}$$

$$B = \frac{z_2 - z_1}{x_2 - x_1}, \quad \theta_1 = \text{atan}\left(\frac{z_1}{x_1}\right), \quad \theta_2 = \text{atan}\left(\frac{z_2}{x_2}\right)$$

$$r_1 = \sqrt{x_1^2 + z_1^2}, \quad r_2 = \sqrt{x_2^2 + z_2^2}$$

Modelación magnética volumen magnetizado



$$V(\vec{x}) = \frac{\mu_0}{4\pi} \int_V \frac{\vec{M}(\vec{x}') \cdot (\vec{x} - \vec{x}')}{|\vec{x} - \vec{x}'|^3} dV'$$

$$\nabla \left(\frac{1}{r} \right) = \nabla \left[\frac{1}{|\vec{x} - \vec{x}'|} \right] = -\frac{\vec{r}}{r^3} = -\frac{\vec{x} - \vec{x}'}{|\vec{x} - \vec{x}'|^3}$$

$$d\vec{s}' = \hat{n} dS' = -\nabla' \left[\frac{1}{|\vec{x} - \vec{x}'|} \right] = -\nabla' \left(\frac{1}{r} \right)$$

$$V(\vec{x}) = \frac{\mu_0}{4\pi} \int_V \vec{M} \cdot \nabla' \left(\frac{1}{r} \right) dV'$$

Utilizando la identidad vectorial:

$$\nabla \cdot (\phi \vec{A}) = \nabla \phi \cdot \vec{A} + \phi \nabla \cdot \vec{A}$$

$$\phi = \frac{1}{r} \quad , \quad \vec{A} = \vec{M}, \text{ se tiene:}$$

$$V(\vec{x}) = \frac{\mu_0}{4\pi} \int_V \nabla' \cdot \left(\frac{\vec{M}}{r} \right) dV' - \frac{\mu_0}{4\pi} \int_V \frac{\nabla \cdot \vec{M}}{r} dV'$$

Utilizando el teorema de la divergencia: $\left(\int_V \nabla \cdot \vec{A} dV = \int_S \vec{A} \cdot d\vec{S} \right)$

$$V(\vec{x}) = \frac{\mu_0}{4\pi} \int_S \frac{\vec{M} \cdot d\vec{S}'}{r} - \frac{\mu_0}{4\pi} \int_V \frac{\nabla \cdot \vec{M}}{r} dV'$$

$$V(\vec{x}) = \frac{\mu_0}{4\pi} \int_S \frac{Q_S}{r} ds' + \frac{\mu_0}{4\pi} \int_V \frac{Q_V}{r} dv'$$

$$Q_S = \vec{M} \cdot \hat{n} \quad , \quad Q_V = -\nabla \cdot \vec{M}$$

Q_S , Q_V se interpretan como "cargas magnéticas" superficiales y volumétricas respectivamente (Blakely, ec. 9.16)

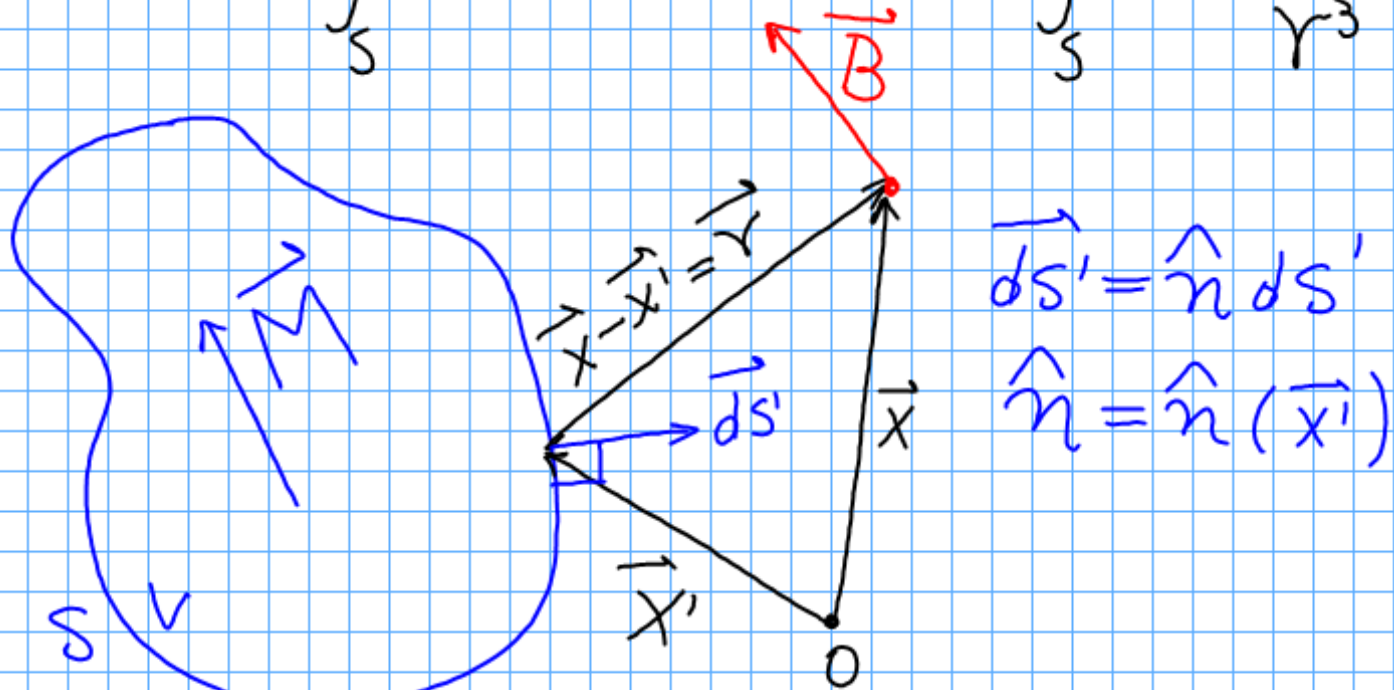
Magnetización constante ($\nabla \cdot \vec{M} = 0$)

$$V(\vec{x}) = \frac{\mu_0}{4\pi} \int_S \frac{\vec{M} \cdot d\vec{s}'}{r} = \frac{\mu_0}{4\pi} \vec{M} \cdot \int_S \frac{d\vec{s}'}{r}$$

$$\therefore \vec{B} = -\nabla V = -\frac{\mu_0}{4\pi} \int_S \nabla \left(\frac{\vec{M} \cdot \hat{n}}{r} \right) dS'$$

$\vec{M} = \text{cte}$, $\hat{n} = \hat{n}(\vec{x}')$ entonces:

$$\vec{B}(\vec{x}) = -\frac{\mu_0}{4\pi} \int_S \vec{M} \cdot \hat{n} \nabla \left(\frac{1}{r} \right) dS' = \frac{\mu_0}{4\pi} \int_S \vec{M} \cdot \hat{n} \frac{\vec{\nabla}}{r^3} dS'$$

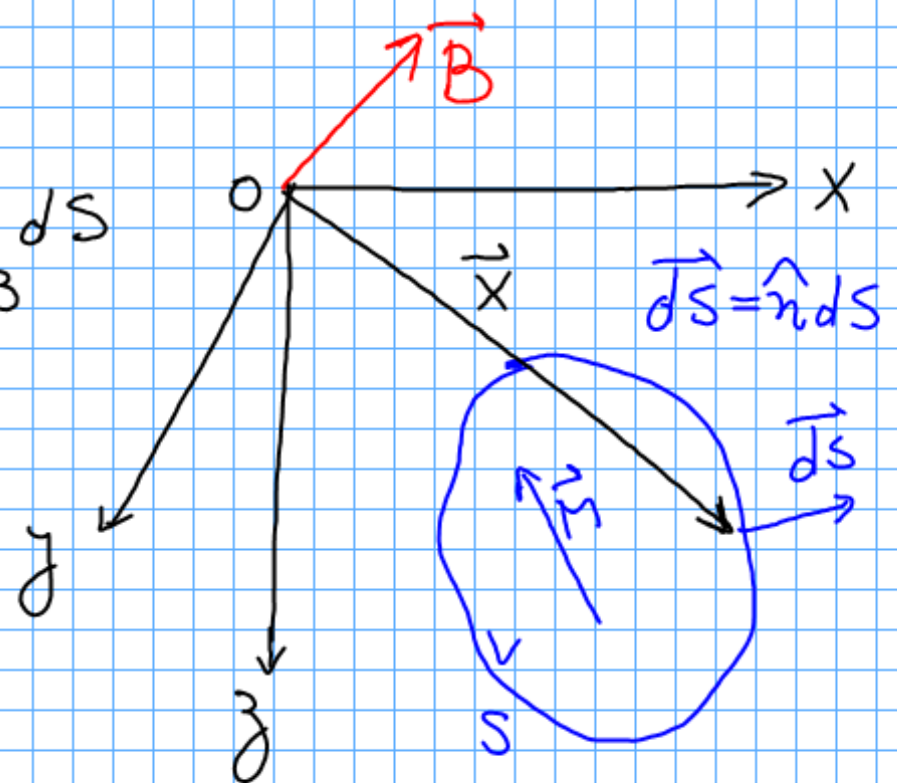


Sin pérdida de generalidad, eligiendo $\vec{x} = 0$, es decir evaluando \vec{B} en el origen, se tiene:

$$\vec{B}(\vec{0}) = -\frac{\mu_0}{4\pi} \int_S \vec{M} \cdot \hat{n} \frac{\vec{x}'}{|\vec{x}'|^3} dS'$$

prescindiendo de las primas $\vec{x}' \rightarrow \vec{x}$, $dS' \rightarrow dS$, para \vec{B} en el origen se tiene:

$$\vec{B}(\vec{0}) = -\frac{\mu_0}{4\pi} \int_S \vec{M} \cdot \hat{n} \frac{\vec{x}}{|\vec{x}|^3} dS$$



La forma mas simple de aproximar un volumen cualquiera, es mediante un poliédrico de N caras planas S_i donde en cada una de ellas el vector unitario normal \hat{n}_i es constante. En estas condiciones la última ecuación se transforma en:

$$\vec{B} = -\frac{\mu_0}{4\pi} \sum_{i=1}^N (\vec{M} \cdot \hat{n}_i) \int_{S_i} \frac{\vec{x}}{|\vec{x}|^3} dS$$

