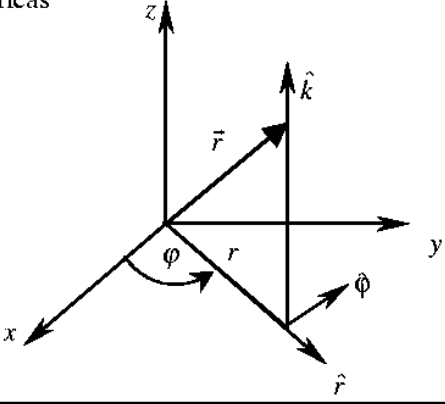
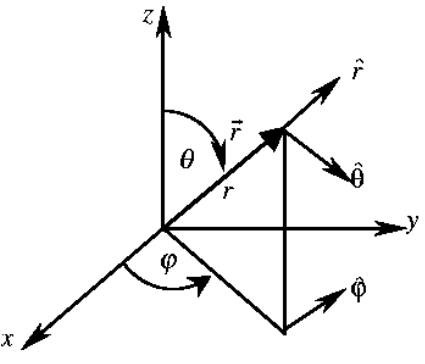


## Formulario Matemático de Electromagnetismo

|   |  |
|---|--|
| <p>C. Cilíndricas</p>  | <p>C. Esféricas</p>    |
| $\vec{r} = r\hat{r} + z\hat{k}$ $x = r \cos \varphi$ $y = r \operatorname{sen} \varphi$ $z = z$         | $\vec{r} = r\hat{r}$ $x = r \operatorname{sen} \theta \cos \varphi$ $y = r \operatorname{sen} \theta \operatorname{sen} \varphi$ $z = r \cos \theta$ |

### 1. Gradientes

|   |   |   |
|---|---|---|
| <p>Cartesianas</p> $\nabla \phi = \frac{\partial \phi}{\partial x} \hat{i} + \frac{\partial \phi}{\partial y} \hat{j} + \frac{\partial \phi}{\partial z} \hat{k}$ | <p>Cilíndricas</p> $\nabla \phi = \frac{\partial \phi}{\partial r} \hat{r} + \frac{1}{r} \frac{\partial \phi}{\partial \varphi} \hat{\varphi} + \frac{\partial \phi}{\partial z} \hat{k}$ | <p>Esféricas</p> $\nabla \phi = \frac{\partial \phi}{\partial r} \hat{r} + \frac{1}{r} \frac{\partial \phi}{\partial \theta} \hat{\theta} + \frac{1}{r \operatorname{sen} \theta} \frac{\partial \phi}{\partial \varphi} \hat{\varphi}$ |
|---|---|---|

### 2. Divergencias

|   |  |
|---|--|
| <p>Cartesianas</p> $\nabla \cdot \vec{A} = \frac{\partial A_x}{\partial x} + \frac{\partial A_y}{\partial y} + \frac{\partial A_z}{\partial z}$   | <p>Cilíndricas</p> $\nabla \cdot \vec{A} = \frac{1}{r} \frac{\partial (rA_r)}{\partial r} + \frac{1}{r} \frac{\partial A_\varphi}{\partial \varphi} + \frac{\partial A_z}{\partial z}$ |
| <p>Esféricas</p> $\nabla \cdot \vec{A} = \frac{1}{r^2} \frac{\partial (r^2 A_r)}{\partial r} + \frac{1}{r \operatorname{sen} \theta} \frac{\partial (\operatorname{sen} \theta A_\theta)}{\partial \theta} + \frac{1}{r \operatorname{sen} \theta} \frac{\partial A_\varphi}{\partial \varphi}$ |  |

### 3. Rotores

|  |
|--|
| <p>Cartesianas</p> $\nabla \times \vec{A} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ A_x & A_y & A_z \end{vmatrix} = \left( \frac{\partial A_z}{\partial y} - \frac{\partial A_y}{\partial z} \right) \hat{i} + \left( \frac{\partial A_z}{\partial x} - \frac{\partial A_x}{\partial z} \right) \hat{j} + \left( \frac{\partial A_y}{\partial x} - \frac{\partial A_x}{\partial y} \right) \hat{k}$  |
| <p>Cilíndricas</p> $\nabla \times \vec{A} = \frac{1}{r} \begin{vmatrix} \hat{r} & r\hat{\varphi} & \hat{k} \\ \frac{\partial}{\partial r} & \frac{\partial}{\partial \varphi} & \frac{\partial}{\partial z} \\ A_r & rA_\varphi & A_z \end{vmatrix} = \frac{1}{r} \left\{ \left( \frac{\partial A_z}{\partial \varphi} - \frac{\partial (rA_\varphi)}{\partial z} \right) \hat{r} + r \left( \frac{\partial A_r}{\partial z} - \frac{\partial A_z}{\partial r} \right) \hat{\varphi} + \left( \frac{\partial (rA_\varphi)}{\partial r} - \frac{\partial A_r}{\partial \varphi} \right) \hat{k} \right\}$   |
| <p>Esféricas</p> $\nabla \times \vec{A} = \frac{1}{r^2 \operatorname{sen} \theta} \begin{vmatrix} \hat{r} & r\hat{\theta} & r \operatorname{sen} \theta \hat{\varphi} \\ \frac{\partial}{\partial r} & \frac{\partial}{\partial \theta} & \frac{\partial}{\partial \varphi} \\ A_r & rA_\theta & r \operatorname{sen} \theta A_\varphi \end{vmatrix}$ $= \frac{1}{r^2 \operatorname{sen} \theta} \left\{ \left( \frac{\partial (r \operatorname{sen} \theta A_\varphi)}{\partial \theta} - \frac{\partial (rA_\theta)}{\partial \varphi} \right) \hat{r} + \left( \frac{\partial A_r}{\partial \varphi} - \frac{\partial (r \operatorname{sen} \theta A_\varphi)}{\partial r} \right) \hat{\theta} + \left( \frac{\partial (rA_\theta)}{\partial r} - \frac{\partial A_r}{\partial \theta} \right) r \operatorname{sen} \theta \hat{\varphi} \right\}$ |

#### 4. Laplacianos

|   |  |
|---|--|
| Cartesianas<br>$\nabla^2 \phi = \frac{\partial^2 \phi}{\partial x^2} + \frac{\partial^2 \phi}{\partial y^2} + \frac{\partial^2 \phi}{\partial z^2}$   | Cilíndricas<br>$\nabla^2 \phi = \frac{1}{r} \frac{\partial}{\partial r} \left( r \frac{\partial \phi}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 \phi}{\partial \varphi^2} + \frac{\partial^2 \phi}{\partial z^2}$ |
| Esféricas<br>$\nabla^2 \phi = \frac{1}{r^2} \frac{\partial}{\partial r} \left( r^2 \frac{\partial \phi}{\partial r} \right) + \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} \left( \sin \theta \frac{\partial \phi}{\partial \theta} \right) + \frac{1}{r^2 \sin^2 \theta} \frac{\partial^2 \phi}{\partial \varphi^2}$ |  |

#### 5. Elementos diferenciales

| De línea  |  |   |
|---|--|---|
| Cartesianas<br>$d\vec{l} = dx\hat{i} + dy\hat{j} + dz\hat{k}$         | Cilíndricas<br>$d\vec{l} = dr\hat{r} + r d\varphi\hat{\varphi} + dz\hat{k}$                  | Esféricas<br>$d\vec{l} = dr\hat{r} + r d\theta\hat{\theta} + r \sin \theta d\varphi\hat{\varphi}$                                     |
| De superficie   |  |   |
| Cartesianas<br>$d\vec{s} = dydz\hat{i} + dx dz\hat{j} + dx dy\hat{k}$ | Cilíndricas<br>$d\vec{s} = r d\varphi dz\hat{r} + dr dz\hat{\varphi} + r dr d\varphi\hat{k}$ | Esféricas<br>$d\vec{s} = r^2 \sin \theta d\theta d\varphi\hat{r} + r \sin \theta dr d\varphi\hat{\theta} + r d\theta dr\hat{\varphi}$ |
| De volumen  |  |   |
| Cartesianas<br>$dv = dx dy dz$  | Cilíndricas<br>$dv = r dr d\varphi dz$   | Esféricas<br>$dv = r^2 \sin \theta dr d\varphi d\theta$   |

donde:

en cartesianas  $\vec{A} = A_x\hat{i} + A_y\hat{j} + A_z\hat{k}$

en cilíndricas  $\vec{A} = A_r\hat{r} + A_\varphi\hat{\varphi} + A_z\hat{k}$

en esféricas  $\vec{A} = A_r\hat{r} + A_\theta\hat{\theta} + A_\varphi\hat{\varphi}$

#### 6. Identidades Vectoriales

$$\nabla \times (\nabla \phi) = 0$$

$$\nabla \cdot (\nabla \times \vec{A}) = 0$$

$$\nabla \times (\nabla \times \vec{A}) = \nabla(\nabla \cdot \vec{A}) - \nabla^2 \vec{A}$$

$$\nabla(\phi\psi) = \phi\nabla\psi + \psi\nabla\phi$$

$$\nabla \cdot (\phi\vec{A}) = \phi\nabla \cdot \vec{A} + \vec{A} \cdot \nabla\phi$$

$$\nabla \times (f(\vec{r})\vec{r}) = 0$$

$$\nabla \left( \frac{1}{r} \right) = -\frac{\vec{r}}{r^3} \quad (\text{con } |\vec{r}| = r)$$

$$\nabla \cdot (\vec{A} \times \vec{B}) = \vec{B} \cdot (\nabla \times \vec{A}) - \vec{A} \cdot (\nabla \times \vec{B})$$

$$\nabla \cdot \vec{r} = 3 \quad \nabla \times \vec{r} = 0$$

$$\nabla(\vec{A} \cdot \vec{r}) = \vec{A}$$

$$\nabla \times (\phi\vec{A}) = \nabla\phi \times \vec{A} + \phi(\nabla \times \vec{A})$$

$$\nabla(\vec{r}^n) = n\vec{r}^{n-2}$$

$$\nabla^2 \left( \frac{1}{r} \right) = \delta(\vec{r})$$

$$\nabla^2 \left( \frac{1}{r} \right) = 0 \quad (\text{para } r \neq 0)$$

$$\nabla \times (\vec{A} \times \vec{B}) = (\vec{B} \cdot \nabla)\vec{A} - (\vec{A} \cdot \nabla)\vec{B} + \vec{A}\nabla \cdot \vec{B} - \vec{B}\nabla \cdot \vec{A}$$

$$\nabla \times (\phi\vec{A}) = \phi\nabla \times \vec{A} - \vec{A} \times \nabla\phi$$