

P1] $r(t) = (R e^{-at} \cos(t), R e^{-at} \sin(t)), t \in [0, \pi]$
 $a > 0, R > 0$

Stärke: exp, cos, sin sind C^1 y Algebra in C^1 ✓

Regulär: $\frac{dr}{dt} = (R e^{-at} (-a \cos(t) - \sin(t)), R e^{-at} (-a \sin(t) + \cos(t)))$

$$\left\| \frac{dr}{dt} \right\| = \sqrt{R^2 e^{-2at} (a^2 \cos^2(t) + 2a \cos(t) \sin(t) + \sin^2(t)) + R^2 e^{-2at} (a^2 \sin^2(t) - 2a \sin(t) \cos(t) + \cos^2(t))}$$

$$= R e^{-at} \sqrt{a^2 (\cos^2(t) + \sin^2(t)) + (\cos^2(t) + \sin^2(t))}$$

$$= R e^{-at} \sqrt{a^2 + 1} > 0 \quad \checkmark$$

Simple: Wenn t_1, t_2 das gilt:

$$r(t_1) = r(t_2) \Rightarrow R e^{-at_1} \cos(t_1) = R e^{-at_2} \cos(t_2) \quad (1)$$

$$R e^{-at_1} \sin(t_1) = R e^{-at_2} \sin(t_2) \quad (2)$$

$$(1)^2 + (2)^2 \Rightarrow R^2 e^{-2at_1} = R^2 e^{-2at_2}$$

$$\Rightarrow -2at_1 = -2at_2 \Rightarrow t_1 = t_2 \rightarrow \text{Simple } \checkmark$$

Langitud
 $t \in [0, \pi]$

$$\int_0^t R e^{-at} \sqrt{a^2 + 1} dt = \frac{R e^{-at} \sqrt{a^2 + 1}}{-a} \Big|_0^t$$

$$\Rightarrow S(t) = \frac{R \sqrt{a^2 + 1}}{a} (1 - e^{-at})$$

P2] Clases hntos ejemplos

P3] a) $M = \int_0^{2\pi} \rho(r(t)) \cdot \left\| \frac{dr}{dt} \right\| dt$, $\rho(r(t)) = a^2 \cos^2(t)$

$$\frac{dr}{dt} = (-a \sin(t), a \cos(t), \frac{h}{2\pi})$$

$$\Rightarrow \left\| \frac{dr}{dt} \right\| = \sqrt{a^2 + \frac{h^2}{4\pi^2}}$$

$$\Rightarrow M = \int_0^{2\pi} a^2 \cos^2(t) \sqrt{a^2 + \frac{h^2}{4\pi^2}} dt = a^2 \sqrt{a^2 + \frac{h^2}{4\pi^2}} \int_0^{2\pi} \frac{1 + \cos(2t)}{2} dt$$

$$= \boxed{a^2 \sqrt{a^2 + \frac{h^2}{4\pi^2}} \cdot \pi}$$

$$X_G \cdot M = \int_0^{2\pi} x(t) \cdot \rho(r(t)) \cdot \left\| \frac{dr}{dt} \right\| dt$$

$$= \int_0^{2\pi} a^3 \cos^3(t) \sqrt{a^2 + \frac{h^2}{4\pi^2}} dt = a^3 \sqrt{a^2 + \frac{h^2}{4\pi^2}} \int_0^{2\pi} \cos(t) - \sin^2(t) \cos(t) dt$$

$$= a^3 \sqrt{a^2 + \frac{h^2}{4\pi^2}} \left(-\frac{\sin^3(t)}{3} \right) \Big|_0^{2\pi} = \boxed{0} \Rightarrow \boxed{X_G = 0}$$

$$Y_G \cdot M = \int_0^{2\pi} y(t) \rho(r(t)) \left\| \frac{dr}{dt} \right\| dt = \int_0^{2\pi} a^3 \cos^2(t) \sin(t) \sqrt{a^2 + \frac{h^2}{4\pi^2}} dt$$

$$= a^3 \sqrt{a^2 + \frac{h^2}{4\pi^2}} \left(-\frac{\cos^3(t)}{3} \right) \Big|_0^{2\pi} = 0 \Rightarrow \boxed{Y_G = 0}$$

$$M \cdot Z_G = \int_0^{2\pi} z(t) \rho(r(t)) \left\| \frac{dr}{dt} \right\| dt = \int_0^{2\pi} a^2 \cos^2(t) \cdot t \cdot \frac{h}{2\pi} \sqrt{a^2 + \frac{h^2}{4\pi^2}} dt = \frac{a^2 h}{2\pi} \sqrt{a^2 + \frac{h^2}{4\pi^2}} \int_0^{2\pi} t \cdot \cos^2(t) dt$$

$$I = \int_0^{2\pi} \frac{t}{2} + \frac{t \cos(2t)}{2} dt = \pi^2 + \frac{1}{2} \int_0^{2\pi} t \cos(2t) dt = \pi^2 + \frac{1}{2} \left(\frac{t \sin(2t)}{2} \Big|_0^{2\pi} - \int_0^{2\pi} \frac{\sin(2t)}{2} dt \right)$$

$$= \pi^2$$

$$M z_G = \frac{a^2 h}{2} \pi \sqrt{a^2 + \frac{b^2}{4\pi^2}}$$

$$\Rightarrow \boxed{z_G = \frac{h}{2}} \quad \Rightarrow \quad \boxed{\text{Centro } G = (0, 0, \frac{h}{2})}$$

$$b) \quad \Gamma(t) = (r \cos(t), r \sin(t)) \Rightarrow \left\| \frac{d\Gamma}{dt} \right\| = r, \quad t \in [0, 2\pi]$$

$$\rho(x, y) = \begin{cases} 2m & y > 0 \\ m & y \leq 0 \end{cases}$$

$$\Rightarrow \rho(\Gamma(t)) = \begin{cases} 2m & t \in (0, \pi) \\ m & t \in [\pi, 2\pi] \end{cases}$$

$$M = \int_0^{2\pi} \rho(\Gamma(t)) \left\| \frac{d\Gamma}{dt} \right\| dt = \int_0^{\pi} \rho(\Gamma(t)) \cdot r dt + \int_{\pi}^{2\pi} \rho(\Gamma(t)) \cdot r dt$$

$$= \int_0^{\pi} 2mr dt + \int_{\pi}^{2\pi} m \cdot r dt = \boxed{3\pi mr}$$

$$X_G \cdot M = \int_0^{2\pi} r \cos(t) \cdot \rho(\Gamma(t)) r dt = \int_0^{\pi} r \cos(t) \cdot 2m \cdot r dt + \int_{\pi}^{2\pi} r \cos(t) m r dt$$

$$= 2mr^2 \cdot \sin(t) \Big|_0^{\pi} + mr^2 \sin(t) \Big|_{\pi}^{2\pi} = 0 \Rightarrow \boxed{X_G = 0}$$

$$Y_G \cdot M = \int_0^{2\pi} r \sin(t) \rho(\Gamma(t)) \cdot r dt = \int_0^{\pi} r \sin(t) \cdot 2m \cdot r dt + \int_{\pi}^{2\pi} r \sin(t) \cdot m \cdot r dt$$

$$= -2mr^2 \cos(t) \Big|_0^{\pi} - mr^2 \cos(t) \Big|_{\pi}^{2\pi} = (4mr^2 - 2mr^2) = 2mr^2$$

$$\Rightarrow \boxed{Y_G = \frac{2}{3}r} \quad \Rightarrow \quad \text{Centro } (0, \frac{2}{3}r)$$

Propuesta: Cambia $\rho(x,y) = m$

$$\Rightarrow \rho(r(\theta)) = m$$

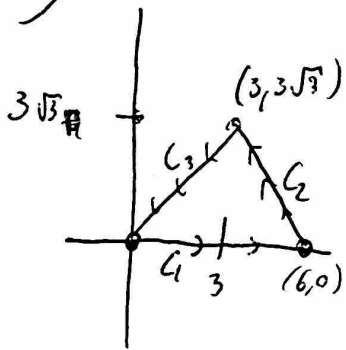
$$M = \int_0^{2\pi} m \cdot r \, dt = 2\pi r m$$

$$X_G \cdot M = \int_0^{2\pi} \cos(\theta) \cdot m \cdot r \, dt = r^2 \cdot m \cdot \sin(\theta) \Big|_0^{2\pi} = 0 \Rightarrow \boxed{X_G = 0}$$

$$Y_G \cdot M = \int_0^{2\pi} r \cdot \sin(\theta) \cdot m \cdot r \, dt = r^2 m (-\cos(\theta)) \Big|_0^{2\pi} = 0 \Rightarrow \boxed{Y_G = 0}$$

es el origen

c)



Es un enunciado con $(0,0)$, $(6,0)$, $(3,3\sqrt{3})$
 $\rho(r(\theta)) = m$ (Uniforme)

$$C_1 \Rightarrow \Gamma_{C_1} = (t, 0), \quad t \in [0, 6]$$

$$C_2 \Rightarrow \Gamma_{C_2} = t(3, 3\sqrt{3}) + (1-t) \cdot (6, 0), \quad t \in [0, 1]$$
$$= (6-3t, 3\sqrt{3} \cdot t)$$

$$C_3 \Rightarrow \Gamma_{C_3} = t \cdot (0, 0) + (1-t)(3, 3\sqrt{3}) \quad t \in [0, 1]$$
$$= (3(1-t), 3\sqrt{3}(1-t))$$

$$M = \int_{C_1} \rho(r(\theta)) \cdot \left\| \frac{dr}{dt} \right\| dt + \int_{C_2} \rho(r(\theta)) \left\| \frac{dr}{dt} \right\| dt + \int_{C_3} \rho(r(\theta)) \left\| \frac{dr}{dt} \right\| dt$$
$$= \int_0^6 m \cdot \overbrace{\|(1, 0)\|}^1 dt + \int_0^1 m \cdot \overbrace{\|(-3, 3\sqrt{3})\|}^6 dt + \int_0^1 m \cdot \overbrace{\|(-3, -3\sqrt{3})\|}^6 dt$$

$$= 6 \cdot m \cdot 1 + m \cdot 6 \cdot 1 + m \cdot 6 \cdot 1 = \boxed{18m}$$

